# Mixing Time in Robotic Explorations 

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## Outline

## (1) Motivation

## (2) Model and Definitions

(3) A Simple Room Example
(4) Pooms

- Comb Room and Snake Room
- A Lego Room
- A General Room Example
(5) Tunnel
- Tilted Tunnel
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## Motivation

- Roomba



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## Model and Definitions

## Room

$\left\{A_{j}=\left[a_{j}, b_{j}\right] \times\left[c_{j}, d_{j}\right]\right\}_{j=1}^{n} \backslash \partial A \backslash w$ $w:=\left\{w_{1}, w_{2}, \cdots\right\}$ is the set of interior walls.


Figure 1: Possible paths taken by the point robot

## Model and Definitions

Motion of the point robot

- Horizontal move $h_{i}$ and Vertical Move $h_{i}$



## Model and Definitions

## Motion of the point robot

- Horizontal move $h_{i}$ and Vertical Move $v_{i}$.
- Step: an ordered pair of moves $\left(h_{i}, v_{i}\right)$.



## Model and Definitions

## Definition of regions



Figure 2: Possible paths of robot starting from the red circle

Figure 3: Definition of regions in a typical room configuration

## Definition (Markov Chain)

A finite Markov Chain is a process which moves among the elements of a finite set $\Omega$ so that when at $x \in \Omega$, the next state is chosen according to a fixed probability distribution $P(x, \cdot)$.



## Definition (Transition Matrix)

The matrix $P$ that that represents the Markov process with state space $\Omega$ is called the transition matrix. $P$ is stochastic. That is, for all $x^{t h}$ row of $P, P(x, \cdot)$ satisfies:

$$
\begin{equation*}
\sum_{y \in \Omega} P(x, y)=1 \tag{1}
\end{equation*}
$$

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$$
\begin{equation*}
\sum_{y \in \Omega} P(x, y)=1 \tag{1}
\end{equation*}
$$

## Theorem

Every eigenvalue $\lambda$ of a stochastic matrix $P$ satisfies $|\lambda| \leq 1$.

## Definition (Stationary Distribution)

A stationary distribution $\pi$ on $\Omega$ satisfies:

$$
\begin{equation*}
\pi=\pi P \tag{2}
\end{equation*}
$$



## Model and Definitions

- Irreducibility :

A transition matrix $P$ is irreducible if $\forall x, y \in \Omega$, there exists integer $t$ such that $P^{t}(x, y)>0$.


- Aperiodicity:

Period is the greatest common divisor of $\tau(x):=\left\{t \geq 1: P^{t}(x, x)>0\right\}$. A transition matrix $P$ is aperiodic if all states have period 1.


## - Reversibility:

A transition matrix is reversible if it satisfies:

$$
\begin{equation*}
\pi(x) P(x, y)=\pi(y) P(y, x) \quad \text { for all } \quad x, y \in \Omega \tag{3}
\end{equation*}
$$



## Definition

The total variation distance ( $T V$ ) between two probability distribution $\mu$ and $v$ on $\Omega$ is defined as the maximum difference between the probabilities assigned to a single event by the two distributions:

$$
\begin{equation*}
\|\mu-v\|_{T V}=\max _{A \subset \Omega}|\mu(A)-v(A)| \tag{4}
\end{equation*}
$$

## Model and Definitions

## Theorem (Convergence Theorem)

Suppose that $P$ is irreducible and aperiodic, with stationary distribution $\pi$. For all $t$, there exists constants $\alpha \in(0,1)$ and $C>0$ such that:

$$
\begin{equation*}
\max _{x \in \Omega}\left\|P^{t}(x, \cdot)-\pi\right\|_{T V} \leq C \alpha^{t} \tag{5}
\end{equation*}
$$

## Model and Definitions

## Definition (Mixing Time)

Let $d(t):=\max _{x \in \Omega}\left\|P^{t}(x, \cdot)-\pi\right\|_{T V}$, then the mixing time $t_{\text {mix }}$ is defined by:

$$
\begin{equation*}
t_{m i x}(\delta):=\min \{t: d(t) \leq \delta\} \tag{6}
\end{equation*}
$$

## Model and Definitions

## Definition (Mixing Time)

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$$
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t_{\operatorname{mix}}(\delta):=\min \{t: d(t) \leq \delta\} \tag{6}
\end{equation*}
$$

Choose $\delta=1 / 100$, and

$$
t_{m i x}:=t_{m i x}(1 / 100)
$$

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## A Simple Room



Figure 4: A simple Room

## A Simple Room



Figure 4: A simple Room


Figure 5: Labeled regions

## A Simple Room



$$
\left.P=\begin{array}{c}
x_{1} \\
x_{2} \\
x_{1} \\
x_{2} \\
x_{3} \\
x_{4}
\end{array} \begin{array}{cccc}
1-\epsilon & 0 & \epsilon & x_{3} \\
x_{4} \\
0 & 1-\epsilon & 0 & \epsilon \\
\frac{1}{2}(1-\epsilon) & \frac{1}{2}(1-\epsilon) & \frac{1}{2} \epsilon & \frac{1}{2} \epsilon \\
\frac{1}{2}(1-\epsilon) & \frac{1}{2}(1-\epsilon) & \frac{1}{2} \epsilon & \frac{1}{2} \epsilon
\end{array}\right) .
$$

## A Simple Room

## Relaxation time $t_{\text {rel }}$

- $P$ is a reversible and stochastic, so we can label its eigenvalues in descending order:

$$
\begin{equation*}
1=\left|\lambda_{1}\right|>\left|\lambda_{2}\right| \geq \cdots \geq\left|\lambda_{|\Omega|}\right| \geq-1 \tag{7}
\end{equation*}
$$

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- Spectral gap of $P$ is $\gamma:=1-\left|\lambda_{2}\right|$


## A Simple Room

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\end{equation*}
$$

- Spectral gap of $P$ is $\gamma:=1-\left|\lambda_{2}\right|$


## Definition (Relexation Time)

The relaxation time $t_{\text {rel }}$ of $P$ with spectral gap $\gamma$ is defined as:

$$
\begin{equation*}
t_{r e l}:=\frac{1}{\gamma} \tag{8}
\end{equation*}
$$

## A Simple Room

Relation between $t_{m i x}$ and $t_{r e l}$ :

## Theorem

Let $\pi_{\text {min }}:=\min _{x \in \Omega} \pi(x)$. For a reversible, irreducible and aperiodic Markov chain with state space $\Omega$, the relation between its relaxation time $t_{r e l}$ and $\pi_{\min }$ can be represented as:

$$
\begin{equation*}
\log \left(\frac{1}{\delta \pi_{m i n}}\right) t_{r e l} \geq t_{m i x}(\delta) \geq\left(t_{r e l}-1\right) \log \left(\frac{1}{2 \delta}\right) \tag{9}
\end{equation*}
$$

## A Simple Room

Relation between $t_{m i x}$ and $t_{r e l}$ :

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\log \left(\frac{1}{\delta \pi_{\min }}\right) t_{r e l} \geq t_{m i x}(\delta) \geq\left(t_{r e l}-1\right) \log \left(\frac{1}{2 \delta}\right) \tag{9}
\end{equation*}
$$

Therefore, $t_{m i x}$ and $t_{r e l}$ are on the same order.

## A Simple Room

- Computation Results: $\left|\lambda_{2}\right|=1-\epsilon$

$$
t_{m i x}=1 / \gamma=1 /(1-\epsilon)=\Theta\left(\frac{1}{\epsilon}\right)
$$

$$
P=\begin{gathered}
x_{1} \\
x_{2} \\
x_{3} \\
x_{4}
\end{gathered}\left(\begin{array}{cccc}
x_{1} & x_{2} & x_{3} & x_{4} \\
1-\epsilon & 0 & \epsilon & 0 \\
0 & 1-\epsilon & 0 & \epsilon \\
\frac{1}{2}(1-\epsilon) & \frac{1}{2}(1-\epsilon) & \frac{1}{2} \epsilon & \frac{1}{2} \epsilon \\
\frac{1}{2}(1-\epsilon) & \frac{1}{2}(1-\epsilon) & \frac{1}{2} \epsilon & \frac{1}{2} \epsilon
\end{array}\right) .
$$

- Computation Results: $\left|\lambda_{2}\right|=1-\epsilon$ $t_{m i x}=1 / \gamma=1 /(1-\epsilon)=\Theta\left(\frac{1}{\epsilon}\right)$.
- Simulation Results:


Figure 6: Simulation Results $n=100$ and $\epsilon=0.001$


Figure 7: Simulation Results $n=1000$ and $\epsilon=0.001$

## Proposition <br> Horizontal (vertical) scaling does not change $t_{m i x}$.

## Proposition

Horizontal (vertical) scaling does not change $t_{m i x}$.

## Definition (Bottleneck Ratio)

After scaling the room to unit dimensions, we define the length of the smallest horizontal (vertical) gap as $\epsilon$, which is also the bottleneck ratio.

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## Comb Room



Figure 8: A "Comb" Shape Room With $N=6$

## Comb Room: Matrix Approach

$$
P=\left(\begin{array}{ll}
P_{11} & P_{12} \\
P_{21} & P_{22}
\end{array}\right)
$$

$P_{11}=(1-\epsilon) I$,
$P_{12}=\epsilon I$,
$P_{21}=\frac{1-\epsilon}{N} J$
$P_{22}=\frac{\epsilon}{N} J$.
$I$ is the $N \times N$ identity matrix, and $J$ is the $N \times N$ matrix with all entries being one.

## Comb Room



- $\left|\lambda_{2}\right|=1-\epsilon$
- $t_{m i x}=\Theta(1 / \epsilon)$


## Snake Room (ouroboric)



Figure 9: An Ouroboric Snake Shape Room With $N=6$

## Ouroboric Snake



Figure 10: An Ouroboric Snake

## Circulant Matrix for ouroboric Snake Room



$$
\begin{aligned}
& \\
& x_{3 n-2} \\
& x_{3 n-1} \\
& x_{3 n}
\end{aligned}\left(\begin{array}{ccccccccc}
x_{3 n-5} & x_{3 n-4} & x_{3 n-3} & x_{3 n-2} & x_{3 n-1} & x_{3 n} & x_{3 n+1} & x_{3 n+2} & x_{3 n+3} \\
\frac{\epsilon}{2} & \frac{1-2 \epsilon}{2} & \frac{\epsilon}{2} & \frac{\epsilon}{2} & \frac{1-2 \epsilon}{2} & \frac{\epsilon}{2} & & & \\
& & & \frac{\epsilon}{2} & 1-2 \epsilon & \epsilon & & & \\
& & & \frac{\epsilon}{2} & \frac{1-2 \epsilon}{2} & \frac{\epsilon}{2} & \frac{\epsilon}{2} & \frac{1-2 \epsilon}{2} & \frac{\epsilon}{2}
\end{array}\right)
$$

The $k^{t h}$ eigenvectors $r_{k}$ has the form:

$$
r_{k}=\left[\begin{array}{c}
a \\
b \\
c \\
a e^{2 \pi i k / N} \\
b e^{-2 \pi i k / N} \\
c e^{-2 \pi i k / N} \\
\vdots \\
a e^{-2 \pi i k(N-1) / N} \\
b e^{-2 \pi i k(N-1) / N} \\
c e^{-2 \pi i k(N-1) / N}
\end{array}\right]
$$

where $k=0,1,2, \cdots, N-1$ and $a, b, c$ are three constants depending on $N$ and $k$.

The $k^{t h}$ eigenvectors $r_{k}$ has the form:

$$
r_{k}=\left[\begin{array}{c}
a \\
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c \\
a e^{2 \pi i k / N} \\
b e^{-2 \pi i k / N} \\
c e^{-2 \pi i k / N} \\
\vdots \\
a e^{-2 \pi i k(N-1) / N} \\
b e^{-2 \pi i k(N-1) / N} \\
c e^{-2 \pi i k(N-1) / N}
\end{array}\right]
$$

where $k=0,1,2, \cdots, N-1$ and $a, b, c$ are three constants depending on $N$ and $k$.
$\lambda\left(\begin{array}{l}a \\ b \\ c\end{array}\right)=\left(\begin{array}{ccc}\epsilon / 2\left(1+e^{\frac{2 \pi i k}{N}}\right) & (1 / 2-\epsilon)\left(1+e^{\frac{2 \pi i k}{N}}\right) & \epsilon / 2\left(1+e^{\frac{2 \pi i k}{N}}\right) \\ \epsilon & 1-2 \epsilon & \epsilon \\ \epsilon / 2\left(1+e^{\frac{-2 \pi i k}{N}}\right) & (1 / 2-\epsilon)\left(1+e^{\frac{-2 \pi i k}{N}}\right) & \epsilon / 2\left(1+e^{\frac{-2 \pi i k}{N}}\right)\end{array}\right)\left(\begin{array}{l}a \\ b \\ c\end{array}\right)$

- Trace: $1-\epsilon+\epsilon \cos \left(\frac{2 \pi k}{N}\right)$
- When $k=1$,

$$
t_{m i x}=\frac{1}{\epsilon\left(1-\cos \left(\frac{2 \pi k}{N}\right)\right)} \approx \frac{N^{2}}{2 \pi^{2} \epsilon}
$$

which is of $\Theta\left(N^{2} / \epsilon\right)$.

## Non-ouroboric Snake

- Shape


Figure 11: non-ouroboric snake shape

## Non-ouroboric Snake

- Coupling Method
- Definitions


## Definition (Coupling of Markov Chains)

A coupling of Markov chains with transition matrix $P$ is a process $\left(X_{t}, Y_{t}\right)_{t=0}^{\infty}$ with the property that both $\left(X_{t}\right)$ and $\left(Y_{t}\right)$ are Markov chains with transition matrix $P$, although the two chains may have different starting distribution.

## Definition $\left(t_{\text {coup }}\right)$

The coupling time $t_{\text {coup }}:=\min \left\{t: X_{t}=Y_{t}\right\}$

## Non-ouroboric Snake

- Coupling Method
- How to bound $t_{\text {mix }}$


## Theorem

Suppose that for each pair of states $x, y \in \Omega$ there is a coupling $\left(X_{t}, Y_{t}\right)$ with $X_{0}=x$ and $Y_{0}=y$. Then, for each such coupling,

$$
\begin{equation*}
d(t) \leq \max _{x, y \in \Omega} P_{x, y}\left\{t_{\text {coup }}>t\right\} \tag{10}
\end{equation*}
$$

## Theorem (Markov's Inequality)

If $X$ is any nonnegative random variable and $a>0$, then

$$
\begin{equation*}
\mathbb{P}(X \geq a) \leq \frac{\mathbb{E}(X)}{a} \tag{11}
\end{equation*}
$$

## Corollary

$$
\begin{equation*}
t_{m i x} \leq 100 E_{x, y}\left(t_{\text {coup }}\right) \tag{12}
\end{equation*}
$$

## Non-ouroboric Snake

- Coupling Method
- Design a coupling


## Definition (Specific coupling design for this case)

For any two points $x, y$, at each step, let $x$ move first and then $y$ move. At each step, $y$ always moves to the same vertical height as $x$. If $x$ and $y$ are in the same chamber, then $y$ also moves to the same horizontal location as $x$.

## Theorem (Observation)

$E_{x, y}\left(t_{\text {coup }}\right)$, in this case, is bounded above by the expected time for one point to move from the first chamber to the last chamber.

## Non-ouroboric Snake

- Redefine States


Figure 12: Simplified States

## Non-ouroboric Snake

- Random Walk On A Graph


Figure 13: Simplified Random Walk On A Graph

## Non-ouroboric Snake

- Solve expected time from $x_{1}$ to $x_{N}$ : If we denote the expected time of moving from the $n^{t h}$ chamber to the last chamber (the $N^{t h}$ ) as $T(n)$, then we would easily obtain a following recurrence relation:

$$
\begin{equation*}
T(n+1)-2 T(n)+T(n-1)+1 / \epsilon=0 \tag{13}
\end{equation*}
$$

with boundary conditions:

$$
\begin{equation*}
T(0)=T(1)+2 / \epsilon, \quad T(N)=0 \tag{14}
\end{equation*}
$$

## Non-ouroboric Snake

- Bound mixing time $t_{m i x}$ : After solving this relation, we find that

$$
\begin{equation*}
T(n)=-\frac{3 n}{2 \epsilon}-\frac{n^{2}}{2 \epsilon}+\frac{3 N}{2 \epsilon}+\frac{N^{2}}{2 \epsilon} \tag{15}
\end{equation*}
$$

Therefore we would have
$t_{\text {mix }} \leq 100 \cdot E\left(t_{\text {coup }}\right) \leq 100 \cdot T(0)=\frac{150 N}{\epsilon}+\frac{50 N^{2}}{\epsilon}$. Therefore, we know that the mixing time $t_{\text {mix }}$ in this case is also bounded above by $O\left(\frac{N^{2}}{\epsilon}\right)$.

## A Lego Room

## Definition

A room is a $n$-Lego room if and only if it consists of $n$ unit chambers and each chamber is connected to at least one other chamber. The walls between any two connected chamber is of length $1-\epsilon$.


Figure 14: An Example of 5-Lego Room

## A Lego Room

- Random Walk


Figure 15: The Equivalent Random Walk On a Graph

## A Lego Room

## Theorem (The Wall Theorem)

The mixing time $t_{m i x}$ for a room increases when the length of one wall is extended and decreases when it is shortened.

## Corollary (Special Case Of The Wall Theorem)

For any random walk on a graph $G$, if the probability between state $i$ and state $j$ is decreased (the probability of staying in $i$ and $j$ is increased), then the mixing time $t_{\text {mix }}$ for this process increases. If such probability is increased, then $t_{m i x}$ decreases.

## A Lego Room

Transformation by the previous Corollary:


Figure 16: A transformation that decreases mixing time

## A Lego Room

Transformation by TWT and its Corollary:


Figure 17: A transformation that increases mixing time

## A Lego Room

## Definition

A red random walk on a graph $G$ is a random walk such that the probability from any vertex $i$ to vertex $j$ of $G$ (in one step) is either 0 or $q \epsilon$, where $q$ is a constant for this walk.


Figure 18: Transformation 1


Figure 19: Transformation 2

## A Lego Room

## Definition (Laplacian Matrix)

Let $G=(V, E)$ be a non-directed finite graph. Let $V$ be the set of vertices and $|V|=N$. Then after choosing a fixed ordering $w_{1}, w_{2}, \ldots, w_{N}$ of the set $V$, the Laplacian matrix is the $N$ by $N$ matrix $A(G)$ whose diagonal entries $a_{i i}$ being the valencies of vertex $i$ and off diagonal entries $a_{i j}=a_{j i}=-1$ if vertex $i$ and $j$ are connected and 0 otherwise.

## Definition (Algebraic Connectivity)

Let $n \geq 2$ and $0 \leq \lambda_{1} \leq \lambda_{2}=a(G) \leq \lambda_{3} \leq \cdots \leq \lambda_{n}$ be the eigenvalues of the matrix $A(G)$. The algebraic connectivity of the graph $G$ is the second smallest eigenvalue $a(G)$.

## A Lego Room

## Theorem (Fiedler, 1973)

Denote $e(G)$ as the edge connectivity of a connected graph $G$, which is the minimal number of edges whose removal would result in losing connectivity of the graph $G$. Then for any $G$, we have

$$
\begin{equation*}
N \geq a(G) \geq e(G)(1-\cos (\pi / N)) \tag{16}
\end{equation*}
$$

Notice that the second largest eigenvalue of transition matrix $P$ for a red random walk on $G$ is $\lambda_{2}=1-q \epsilon a(G)$.

## Theorem (Mixing Time for A Lego Room)

If a room is a $N$-Lego room, then the mixing time $t_{m i x}$ for this room is bounded below from $O\left(\frac{1}{N \epsilon}\right)$ and bounded above by $O\left(\frac{N^{2}}{\epsilon}\right)$.

## A General Room



Figure 20: A Room


Figure 21: Adding Walls

## A General Room

## Lemma

For any room, the number of states is on the order of $O(s)$, where $s$ is the number of sides.

## Lemma

The probability between any two connected states is bigger than or equal to $\epsilon$.

Then by TWT, we can decrease the probability from any state $i$ to any other state $j$ to $\epsilon$ with $t_{m i x}$ increasing. Therefore, $t_{\text {mix }}$ for the original room is bounded by $t_{\text {mix }}$ for a red random walk.

## Theorem

For any room with $s$ many number of sides and $\epsilon$ bottleneck ratio, the mixing time $t_{\text {mix }}$ is bounded above by $O\left(\frac{s^{2}}{\epsilon}\right)$

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## Tilted Tunnel

- Shape


Figure 22: A Tilted Tunnel

## Tilted Tunnel



Figure 23: A Tilted Tunnel

$$
\begin{gathered}
P \rho(s, h, t)=\rho(s, h, t+1)=\frac{1}{B} \iint_{D_{B}} \rho(u, r, t) d u d r \\
\rho(s, h, t+1)=\sum_{k=0}^{\infty} a_{k}(t+1) e^{2 \pi i k s / L}=\frac{1}{B} \iint_{D_{B}} \rho(u, r, t) d u d r \\
=\frac{1}{B} \iint_{D_{B}} \sum_{k=0}^{\infty} a_{k}(t) e^{2 \pi i k u / L} d u d r=\frac{1}{B} \sum_{k=0}^{\infty} \iint_{D_{B}} a_{k}(t) e^{2 \pi i k u / L} d u d r
\end{gathered}
$$

## Tilted Tunnel

$$
\begin{gather*}
a_{k}(t+1) e^{2 \pi i k s / L}=\frac{1}{B} \iint_{D_{B}} a_{k}(t) e^{2 \pi i k u / L} d u d r  \tag{18}\\
a_{k}(t+1)=\frac{L^{2} \sin ^{2}(2 \alpha)}{4 \epsilon^{2} k^{2} \pi^{2}} \sin \left(\frac{2 \epsilon k \pi}{L \sin (2 \alpha)}\right) a_{k}(t)=\Phi(k) a_{k}(t) \tag{19}
\end{gather*}
$$

where $\Phi(k)$ is the eigenvalues in this case. When $k=1$, such value is the second largest.

## Theorem (Mixing Time For Tilted Tunnel)

For a Tunnel of length $L$ and width $\epsilon$, where $\epsilon \ll L$, the mixing time $t_{\text {mix }}$ is on the order of $O\left(\frac{\sin ^{2}(2 \alpha) L^{2}}{\epsilon^{2}}\right)$

## Bent Tunnel

## Conjecture

For any bent tunnel $L$ with width $\epsilon$, where $\epsilon \ll L$, we denote $\alpha(s)$ as the angle of the tunnel with horizontal axis at point $s$. Then

$$
\begin{equation*}
t_{\text {rel }}=\frac{3}{4 \pi^{2} \epsilon^{2}}\left(\int_{L}|\sin (2 \alpha(s))| d s\right)^{2} \tag{20}
\end{equation*}
$$

Experimentation:


Figure 24: An Example


Figure 25: Discretization

## Bent Tunnel

Some data: 90 by 90 pixels discretization


Figure 26: Expected Result to Discretizated Result

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