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Javelins

Singularities of Hinge Structures

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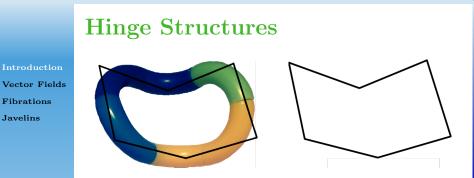




Origin



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Definition

A hinge structure is a piecewise linear embedding of I = [0, 1] into \mathbb{R}^3 . We call the hinge vectors $v_0, v_1, \ldots, v_{k-1}$ and the vertices p_0, p_1, \ldots, p_k $(v_i = p_{i+1} - p_i)$. In a closed configuration, $p_0 = p_k$. (For closed structures, we have an embedding of S^1 .)

Singularities

The angles between consecutive hinge vectors are fixed, but the hinges are free to rotate.

The set of positions is parametrized by the k-1-dimensional torus, T^{k-1} , and we have a map $\tau: T^{k-1} \longrightarrow W_1(\mathbb{R}^3)$, which gives the position of an end-frame that we attach to p_{k-1} .

We are looking for configurations $x \in T^{k-1}$ where τ has a singularity. In other words, we want to find all the positions where the motion of τ is restricted.

Definition

A hinge structure is **singular** in a given configuration x if τ is singular at x.

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Exterior Vectors

Definition

The exterior (or wedge) product, denoted by \wedge , is a multilinear operation on a vector space V that is associative and collapses $v \wedge v$ to 0.

Exterior products are anticommutative: $v \wedge w = -w \wedge v.$

For any vector space V over a field F, the set

$$\underbrace{V \land V \land \dots \land V}_{n \text{ times}} = \bigwedge^n V$$

is also a vector space over F.

Associated Vectors

Definition

The associated exterior vector α_i to a hinge v_i is the exterior 2-vector $\alpha_i = (e_4 + p_i) \wedge v_i$.

It has been shown [Borcea, et. al] that a configuration is singular if and only if its associated exterior vectors don't span $\mathbb{R}^4 \wedge \mathbb{R}^4$.

Corollary

Singularity is preserved by linear transformations.

Theorem (Projective Intersection Theorem) If there exists a line that intersects or is parallel to each hinge, the configuration is singular.

Helical Vector Fields

If a hinge structure is singular, the exterior vectors corresponding to hinges all lie in some hyperplane.

Theorem (Helicity Theorem)

A closed hinge structure is singular if and only if there is some vector field V on \mathbb{R}^3 of the form

$$V(\vec{x}) = (\vec{x} - \vec{a}) \times \vec{n} + c * \vec{n}$$

that for every vertex p_i and hinge vector $v_i = p_{i+1} - p_i$ satisfies

$$V(p_i) \cdot v_i = 0$$

We call V a helical vector field, or helicity.

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Reformulation

A helical vector field V has the property that if a straight line γ satisfies

 $\dot{\gamma}(t) \cdot V(\gamma(t)) = 0.$

for some $t \in \mathbb{R}$, then it satisfies this equation for all real t. This is a very nice property.

Theorem (Helicity Theorem, Reformulated) A closed hinge structure H is singular if and only if there exists a helical vector field to which H, considered as a piecewise linear loop, travels at all times perpendicular.

Hyperboloids

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Take the set of all vectors based in some plane perpendicular to the symmetry axis. The span of all the vectors is a partition of \mathbb{R}^3 by lines. This is a very special property of V.

If we consider only the subset of vectors whose basepoints lie some fixed distance from the symmetry axis, we get a hyperboloid. This means that given our planar subset of \mathbb{R}^3 , V induces a partition of \mathbb{R}^3 determined by this choice of plane.

Ruled Lines

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Singularities of Hinge Structures

What Is the Hopf Fibration?

Definition

The **Hopf fibration** is a many-to-one continuous map from the three-sphere to the two-sphere where the preimage of each point is a great circle. It is a way to locally write S^3 as $S^1 \times S^2$.

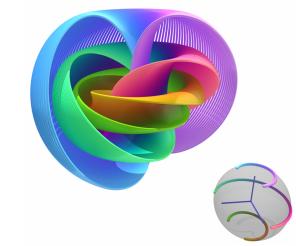
If we embed \mathbb{R}^3 into \mathbb{R}^4 like before, we can "map" \mathbb{R}^3 onto S^3 by sending the point p to $\pm p/||p||$ and projectively completing.

Theorem (Hopf Fibration Theorem)

For c = 1 and the symmetry axis of V coinciding with the z-axis in \mathbb{R}^3 , the ruled lines of the hyperboloids are the fibers of the Hopf fibration.

The Hopf Fibration

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Classification by Fibrations

Definition

The **hinge-normal vector** n_i corresponding to the *i*th vertex p_i is given by $n_i = v_{i-1} \times v_i$.

Suppose that we translate all hinge-normal vectors along the symmetry axis so that their basepoints are coplanar. Then the configuration is singular if and only if every resulting vector lies along a ruled line.

Theorem (Fibration Theorem)

If we have a singular configuration and we translate our hinge-normal vectors like above, then there exists a fibration of S^3 over S^2 with great circles as fibers that sends the hinge-normal vectors to single points.

What Is a Javelin?

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Definition

A **javelin** J_i corresponding to the *i*th vertex p_i is the line given by the intersection of the two planes determined the sets $\{p_{i-2}, p_{i-1}, p_i\}$ and $\{p_i, p_{i+1}, p_{i+2}\}$, where we take the indices modulo kif necessary.

Why Javelins?

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- Question: How do you determine when a hinge structure is singular?
- ▶ Can move along javelins and stay singular.
- ► Know the value of the helical vector field on the javelins, if it exists

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Algorithm for Determining Singularity

- ▶ Want to first find upward direction for helicity
- ▶ Value of the vector field on "sphere at infinity"
- Once upward direction is known, can project onto plane perpendicular to the upward direction
- Simple trigonometry to get the axis of the helicity
- Upward rise of vector field relative to plane perpendicular gives c

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5 Points Theorem

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- ► Take any five points in ℝ³ that don't all lie in a plane
- ► Then the vectors $\hat{J}_i \times (p_{i+1} p_{i-1})$ all lie in some plane

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Space of Singular Configurations

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- We can move vertices along javelins and stay singular
- ► Through such motions, we can collapse any hinge structure to a point
- Space of singular configurations is maybe a "cone"

Further Directions

- Introduction Vector Fields Fibrations
- ► Flowing a hinge structure along javelins
 - ▶ Configuration spaces of hinge structures
 - Schubert calculus

References

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- Vector Fields
- Fibrations
- Javelins

Borcea, C. and I. Streinu. *Singularities of Hinge Structures.* arXiv:0812.1373v1.