Two added structures in sparse recovery: nonnegativity and disjointedness

> Simon Foucart University of Georgia

Semester Program on "High-Dimensional Approximation" ICERM 7 October 2014

Part I: Nonnegative Sparse Recovery

(joint work with D. Koslicki)

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- Codes available at sourceforge.net/projects/quikr/ sourceforge.net/projects/wgsquikr/

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Connection with OMP explains suitability for sparse recovery.

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• We prefer the ℓ_1 -squared regularization

$$\underset{\mathbf{z} \in \mathbb{R}^N}{\text{minimize}} \|\mathbf{z}\|_1^2 + \lambda^2 \|\mathbf{y} - \mathbf{A}\mathbf{z}\|_2^2 \qquad \text{subject to} \quad \mathbf{z} \geq \mathbf{0},$$

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When y = Ax + e with e ≠ 0, a classical strategy consists in solving the ℓ₁-regularization

$$\underset{\mathbf{z} \in \mathbb{R}^N}{\text{minimize}} \|\mathbf{z}\|_1 + \nu \|\mathbf{y} - \mathbf{A}\mathbf{z}\|_2^2 \qquad \text{subject to} \quad \mathbf{z} \geq \mathbf{0}.$$

• We prefer the ℓ_1 -squared regularization

$$\underset{\mathbf{z} \in \mathbb{R}^N}{\text{minimize}} \|\mathbf{z}\|_1^2 + \lambda^2 \|\mathbf{y} - \mathbf{A}\mathbf{z}\|_2^2 \qquad \text{subject to} \quad \mathbf{z} \geq \mathbf{0} ,$$

because it is recast as the Nonnegative Least Squares problem

$$\begin{split} & \underset{\textbf{z} \in \mathbb{R}^{N}}{\text{minimize}} \| \widetilde{\textbf{y}} - \widetilde{\textbf{A}} \textbf{z} \|_{2}^{2} & \text{subject to} \quad \textbf{z} \geq \textbf{0}, \\ & \text{where } \widetilde{\textbf{A}} = \frac{\begin{bmatrix} 1 & \cdots & 1 \\ & \lambda \textbf{A} \end{bmatrix}}{\begin{bmatrix} \lambda \textbf{A} \end{bmatrix}} \text{ and } \widetilde{\textbf{y}} = \frac{\begin{bmatrix} 0 \\ & \lambda \textbf{y} \end{bmatrix}}{\begin{bmatrix} \lambda \textbf{y} \end{bmatrix}}. \end{split}$$

When y = Ax + e with e ≠ 0, a classical strategy consists in solving the ℓ₁-regularization

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where
$$\widetilde{\mathbf{A}} = \begin{bmatrix} 1 & \cdots & 1 \\ & \lambda \mathbf{A} \end{bmatrix}$$
 and $\widetilde{\mathbf{y}} = \begin{bmatrix} 0 \\ \lambda \mathbf{y} \end{bmatrix}$.

For frequency matrices, as λ → ∞, the minimizer x_λ tends to the minimizer of ||z||₁ subject to Az = y and z ≥ 0.

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• Decompose vectors $\mathbf{z} \in \mathbb{R}^N$ as $\mathbf{z} = \mathbf{z}_+ - \mathbf{z}_-$ with $\mathbf{z}_+, \mathbf{z}_- \in \mathbb{R}^N_+$.

- Decompose vectors $z \in \mathbb{R}^N$ as $z = z_+ z_-$ with $z_+, z_- \in \mathbb{R}^N_+$.
- The ℓ_1 -squared regularization

(REG) minimize
$$\|\mathbf{z}\|_1^2 + \lambda^2 \|\mathbf{y} - \mathbf{A}\mathbf{z}\|_2^2$$

is recast as the Nonnegative Least Squares problem

$$\begin{array}{ll} \mathrm{minimize} & \|\widetilde{\mathbf{y}} - \widetilde{\mathbf{A}} \widetilde{\mathbf{z}}\|_2^2 & \text{subject to } \widetilde{\mathbf{z}} \geq \mathbf{0}, \\ \\ \text{where } \widetilde{\mathbf{y}} = \frac{\begin{bmatrix} \mathbf{0} \\ \lambda \mathbf{y} \end{bmatrix}}, \widetilde{\mathbf{A}} = \frac{\begin{bmatrix} \mathbf{1} & \cdots & \mathbf{1} \\ \lambda \mathbf{A} & | & -\lambda \mathbf{A} \end{bmatrix}}, \widetilde{\mathbf{z}} = \frac{\begin{bmatrix} \mathbf{z}_+ \\ \mathbf{z}_- \end{bmatrix}}. \end{array}$$

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$$\|\mathbf{x} - \mathbf{x}_{\lambda}\|_{1} \leq C \sigma_{s}(\mathbf{x})_{1} + D\sqrt{s} \|\mathbf{e}\|_{2} + \frac{E s}{\lambda^{2}} \|\mathbf{x}\|_{1}$$

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Part II: Disjointed Sparse Recovery

(joint work with M. Minner and T. Needham)

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• $\mathbf{x} \in \mathbb{R}^N$: positions of airplanes relative to a discretized grid.

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 Few airplanes that are not too close to one another: sparsity and disjointedness.

- $\mathbf{x} \in \mathbb{R}^N$: positions of airplanes relative to a discretized grid.
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- Disjointedness is also relevant to model neural spike trains. [Hedge–Duarte–Cevher 09]

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• We say that $\mathbf{x} \in \mathbb{R}^N$ is *s*-sparse and *d*-disjointed if

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- We say that $\mathbf{x} \in \mathbb{R}^N$ is *s*-sparse and *d*-disjointed if
 - **x** has no more than *s* nonzero entries,
 - there are $\geq d$ zero entries between two nonzero entries.

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The minimal number of linear measurements for the recovery of all s-sparse vectors is

$$m_{\rm spa} \asymp s \ln\left(e \frac{N}{s}\right).$$

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The minimal number of linear measurements for the recovery of all s-sparse vectors is

$$m_{\mathrm{spa}} \asymp s \ln \left(e \frac{N}{s} \right)$$

The minimal number of linear measurements for the recovery of all *d*-disjointed vectors is [Candès–Fernandez-Granda 14]

$$m_{\rm dis} \asymp \frac{N}{d}.$$

The minimal number of linear measurements for the recovery of all s-sparse vectors is

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There is no benefit in knowing the simultaneity of sparsity and disjointedness over knowing only one of the structures, since

$$m_{
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m spa}, m_{
m dis}\}$$
 .

Sparse Disjointed Supports

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There are

$$\binom{N-d(s-1)}{s} \leq \left(e\frac{N-d(s-1)}{s}\right)^s$$

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The adaptation of iterative hard thresholding is

$$\mathbf{x}^{n+1} = \mathbf{P}_{s,d}(\mathbf{x}^n + \mathbf{A}^*(\mathbf{y} - \mathbf{A}\mathbf{x}^n)),$$

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$$\|\mathbf{x} - \lim_{n \to \infty} \mathbf{x}^n\|_2 \le D \|\mathbf{e}\|_2$$

as soon as the RI-like property

 $(1-\delta)\|\mathbf{z}+\mathbf{z}'+\mathbf{z}''\|_{2}^{2} \leq \|\mathbf{A}(\mathbf{z}+\mathbf{z}'+\mathbf{z}'')\|_{2}^{2} \leq (1+\delta)\|\mathbf{z}+\mathbf{z}'+\mathbf{z}''\|_{2}^{2}$

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- The latter occurs w/hp for $m \ge C\delta^{-2}\ln(e(N-d(s-1))/s)$.
- Similar results obtained earlier for the adaptation of CoSaMP.

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- [Hedge–Duarte–Cevher 09] propose an integer program relaxed to a linear program that is solved in $\mathcal{O}(N^{3.5})$ operations.
- A dynamic program can be solved in $\mathcal{O}(N^2)$ operations.
- Determine F(N, s), where

$$F(n,r) := \min\left\{\sum_{j=1}^{n} |x_j - z_j|^2 : \mathbf{z} \in \mathbb{C}^n \text{ } r\text{-sparse } d\text{-disjointed}\right\}$$
$$= \min\left\{\frac{F(n-1,r) + |x_n|^p,}{F(n-d-1,r-1) + \sum_{j=n-d}^{n-1} |x_j|^p.}\right\}$$

Dynamic program for $\mathbf{x} = (1, 0, 1, 2^{1/4}, 1, 0, 2^{-1/2})$, s = 3, d = 1.

X	<i>F</i> (<i>n</i> , <i>r</i>)	<i>r</i> = 0	r = 1	<i>r</i> = 2	<i>r</i> = 3
1	n = 1	1 5	0	0 ~	0
0	n = 2	1	0	0	0
1	<i>n</i> = 3	2	1	0	0
1.1892	<i>n</i> = 4	3.4142	<u>}</u> 2	\uparrow 1	1
1	<i>n</i> = 5	4.4142	<mark>, 3</mark>	<u>↑</u> 2	1.4142
0	<i>n</i> = 6	4.4142	, 3	<u>↓</u> 2	1.4142
0.7071	n=7	4.9142	3.5	2.5	1.9142

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Noninflating measurements relative to our model:

 $\|\mathbf{A}\mathbf{z}\|_2 \leq c \|\mathbf{z}\|_2$ whenever \mathbf{z} is *s*-sparse *d*-disjointed.

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Then

$$m \geq C s \ln \left(e \frac{N - d(s-1)}{s} \right).$$

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There exist

$$n\geq \left(\frac{N-d(s-1)}{c_1s}\right)^{c_2s}$$

d-disjointed subsets S_1, \ldots, S_n of $\llbracket 1 : N \rrbracket$ such that

$$\operatorname{card}(S_i) = s$$
 for all i , $\operatorname{card}(S_i \cap S_j) < \frac{s}{2}$ for all $i \neq j$.

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This extends a crucial result known for d = 0 (sparse vectors), but the counting argument must be somewhat refined.