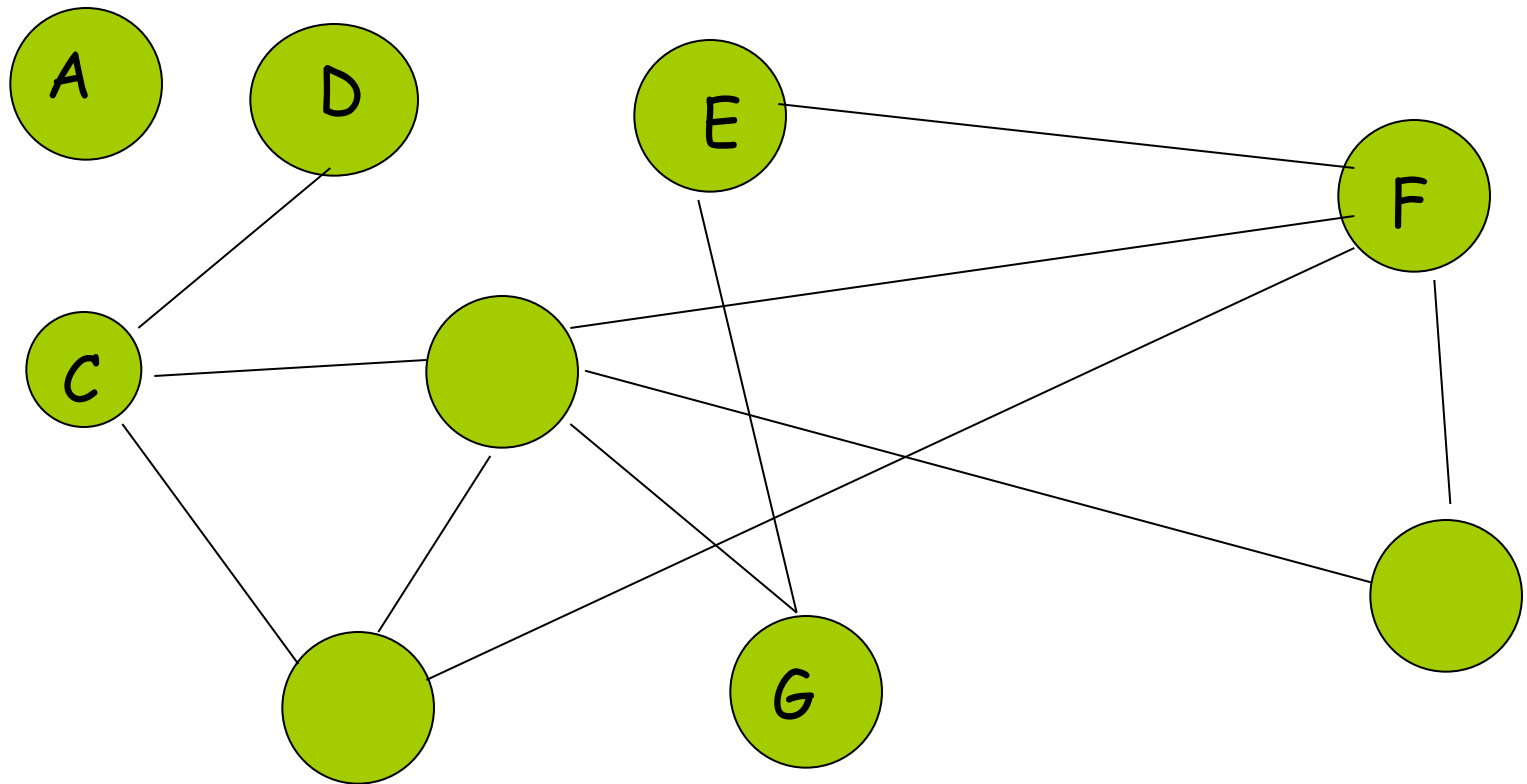


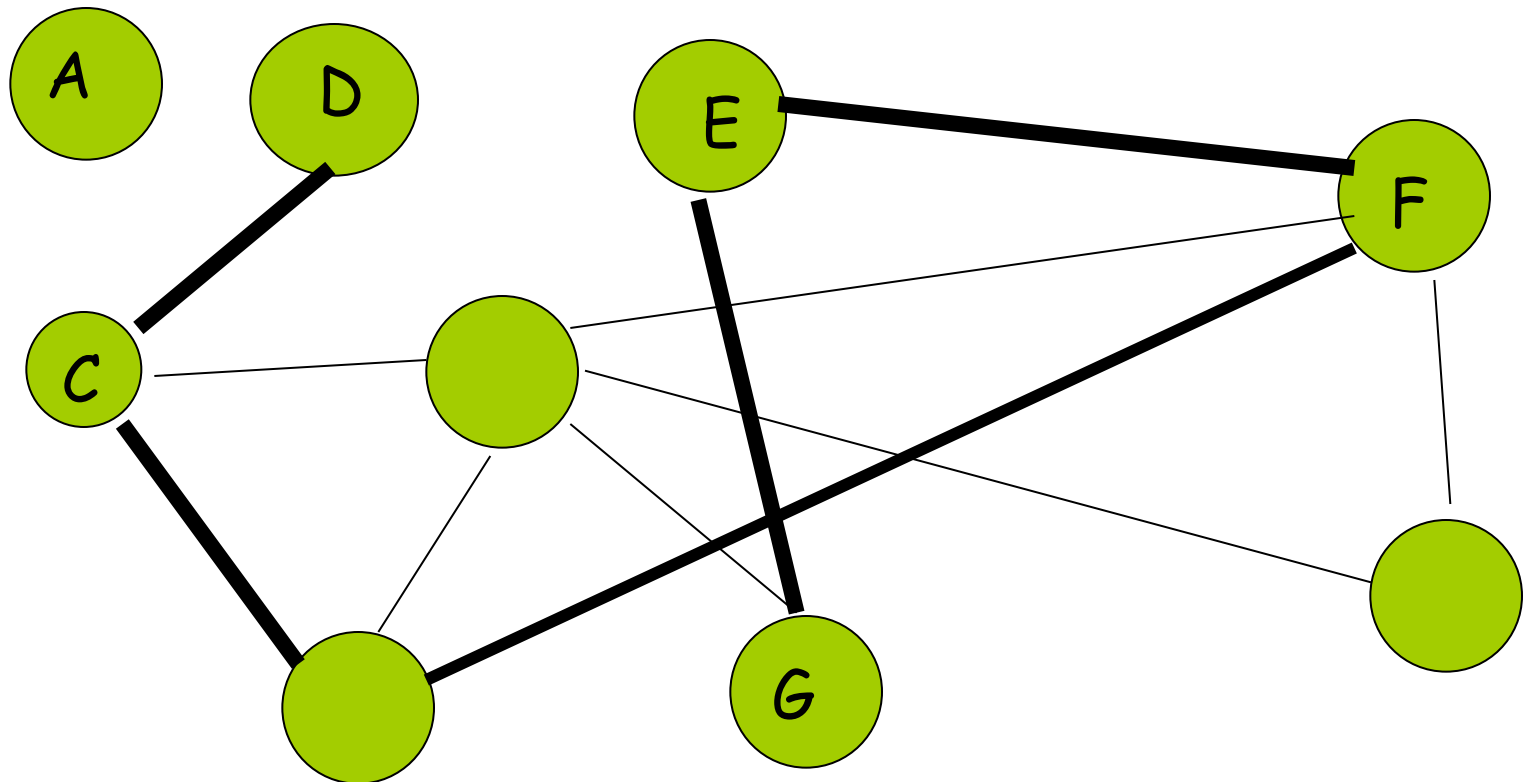
Impromptu Updating of MST and ST in a Distributed Dynamic Graph

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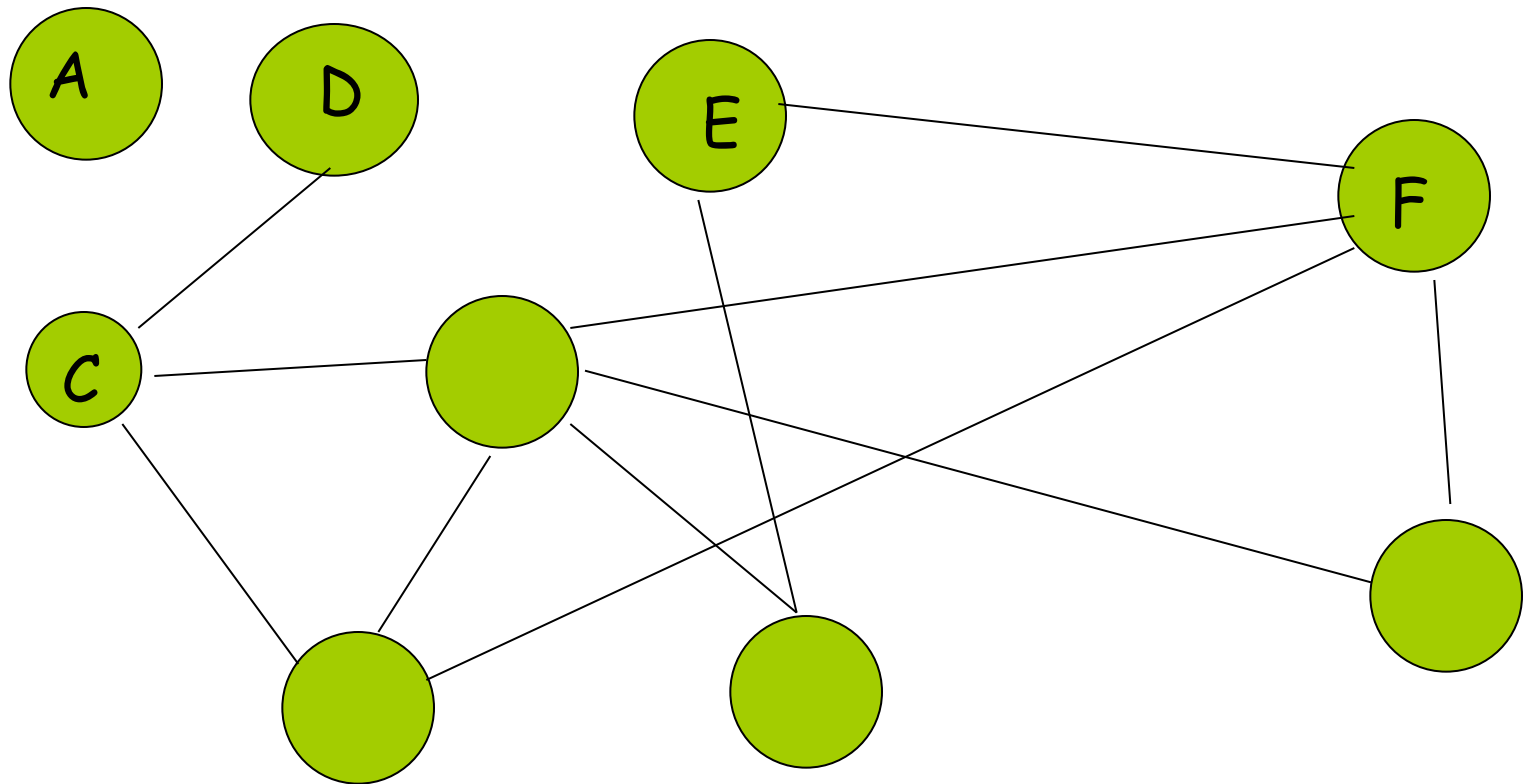
Network with n nodes, m edges
Each node has list of incident edges
and edge weights. Nodes have
distinct IDs



A network maintains a subgraph if its edges are marked by their endpoints

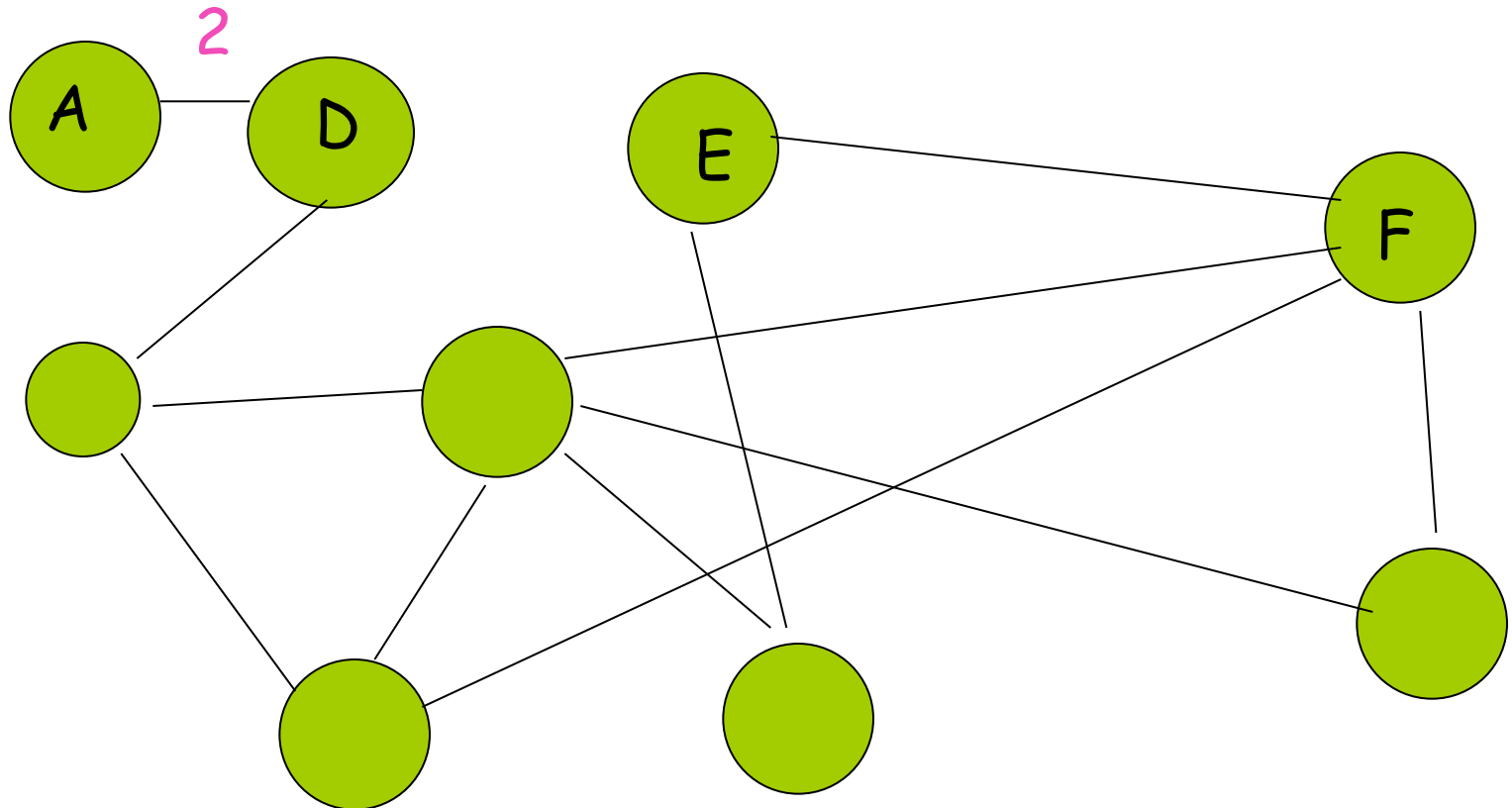


Communication: Each node may send messages of size $O(\log n)$ to all its neighbors in a single step.
Synchronous vs. Asynchronous

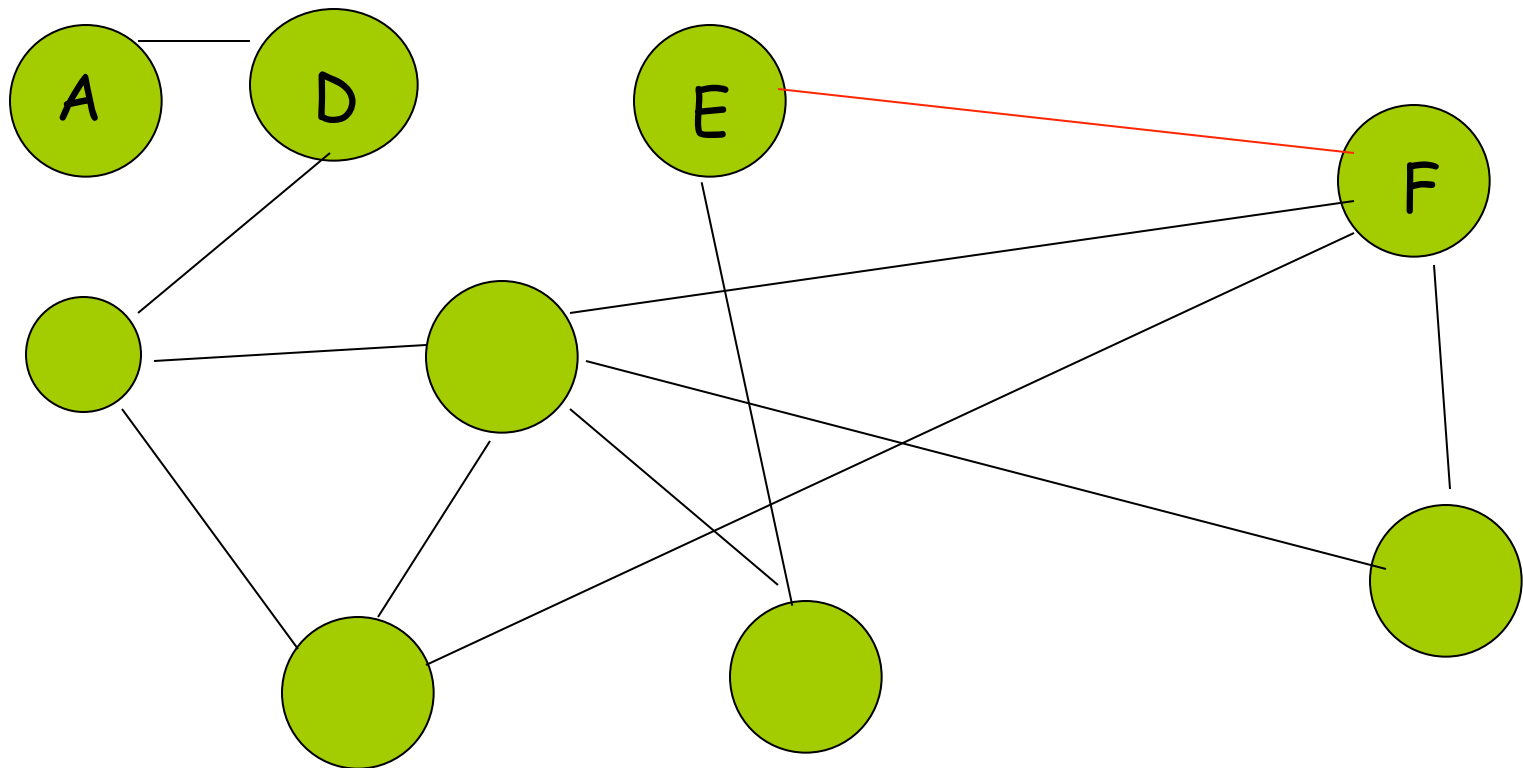


UPDATES:

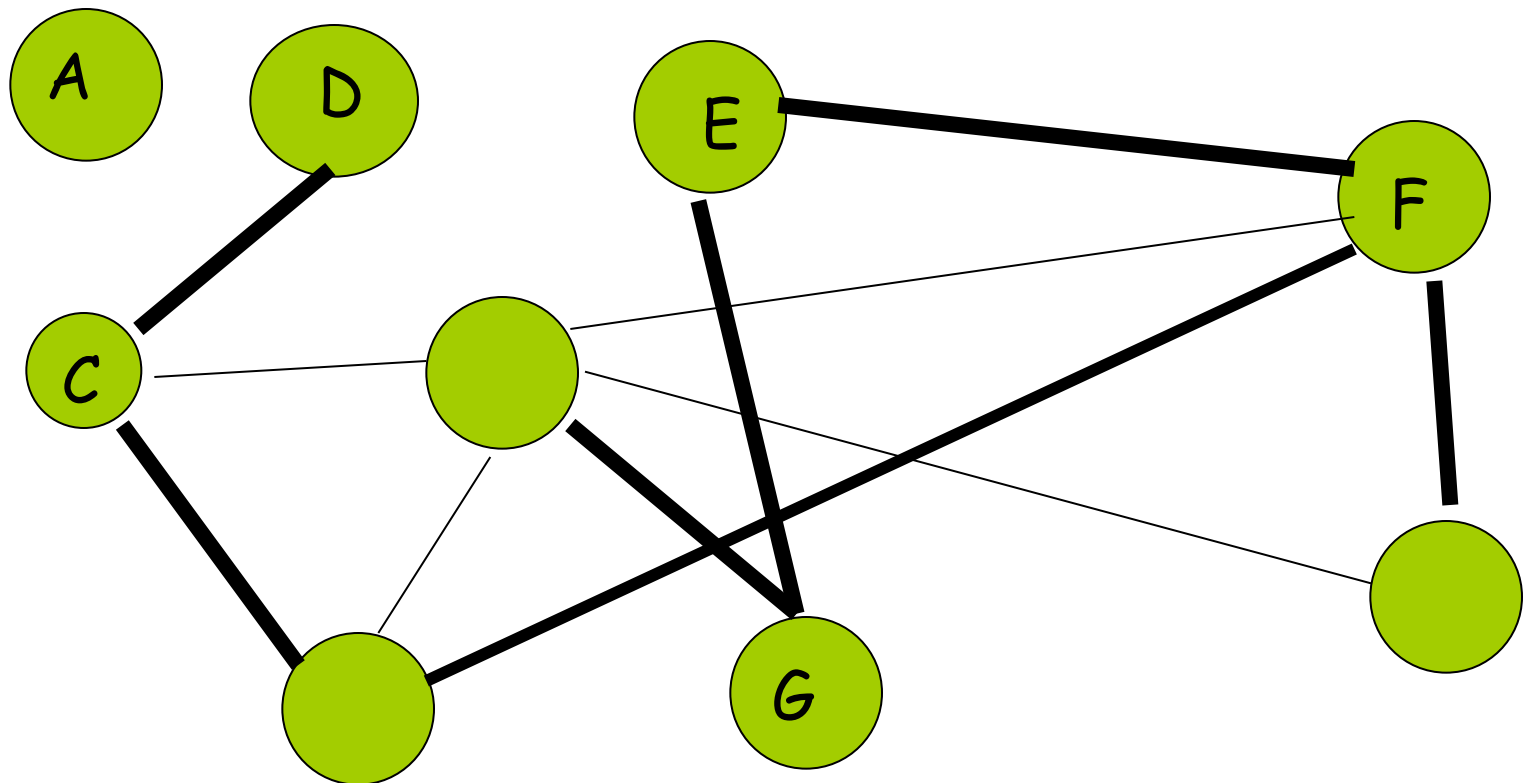
Insert ({A,D}, edge_weight)



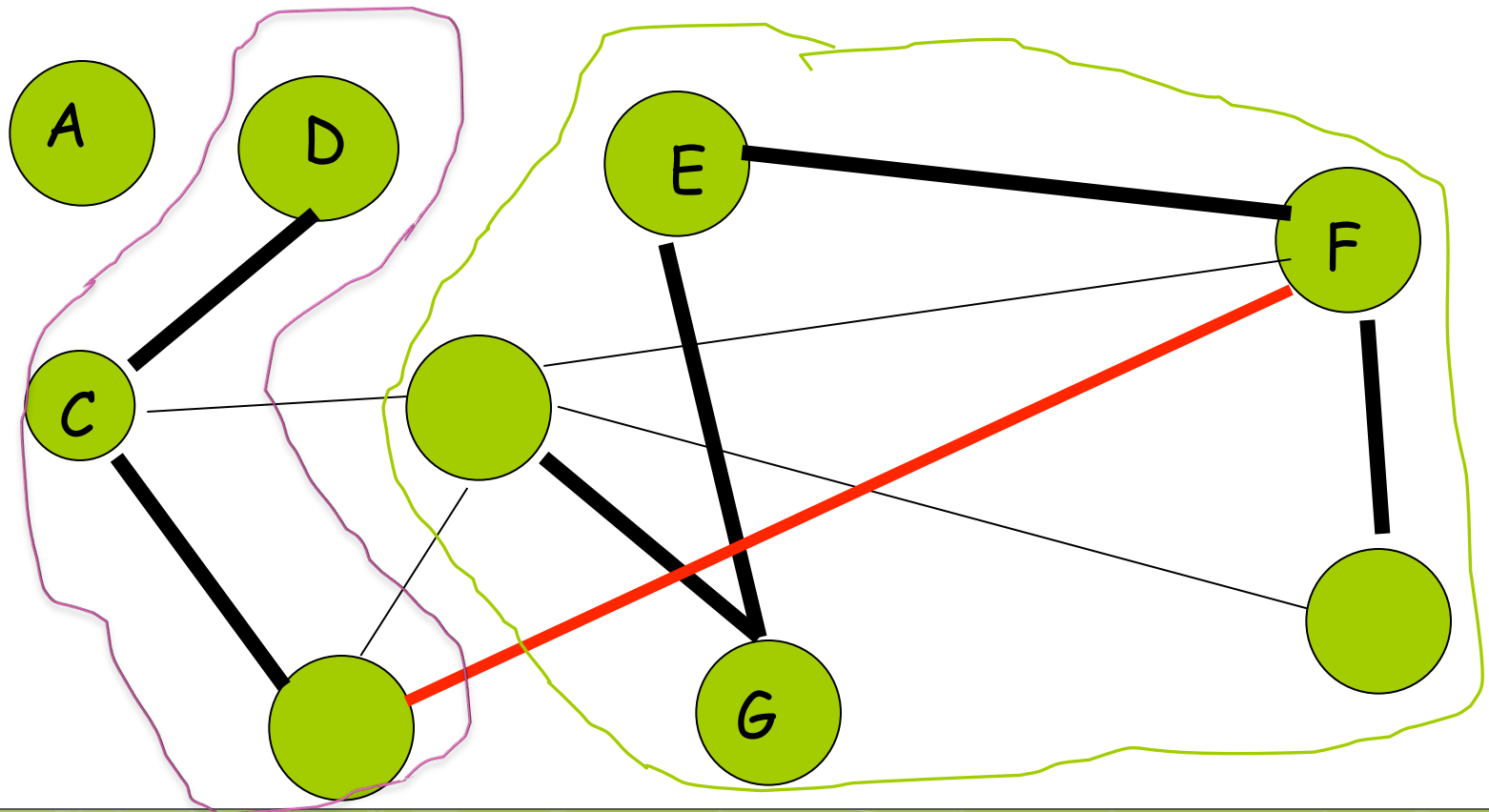
Delete edge {E,F}



MST (resp. ST) Problem: Maintain a minimum spanning forest (resp., spanning forest) in a dynamic network



Main difficulty:
How to find a **replacement edge**
when a tree edge is deleted



Our contribution:

A New Tool

for finding, **impromptu**, a replacement edge w.h.p.

for MST: an edge of min cost leaving a tree in a graph

for ST: any edge leaving a tree in a graph

Costs:

MST / ST

Message complexity $O(n \log n)$, $O(n)$ (expected)

Preprocessing Time NONE

Update Time: $O(\text{diam}(\text{tree}) * \log n)$, $O(\text{diam}(\text{tree}))$
expected.

Local memory needed NONE
between updates

previous distributed dynamic MST:

Awerbuch, Cidon, Kutten:1990, 2008
 $O(n)$ messages--First dynamic
updating
in $o(m)$ messages per update.

But local memory=
 $O(n \cdot \text{degree of node} \cdot \log n)$
Stores the forest in each node ;

Static MST/ST thought to require m messages!

Gallagher, Humblet and Spira(1983)

$O(m + n \log n)$ messages for building one from scratch (asynchronously)

Our method yields $O(n \log^2 n)$ messages for constructing an MST in the synchronous model.

NOT KNOWN if m can be avoided for the asynchronous model.

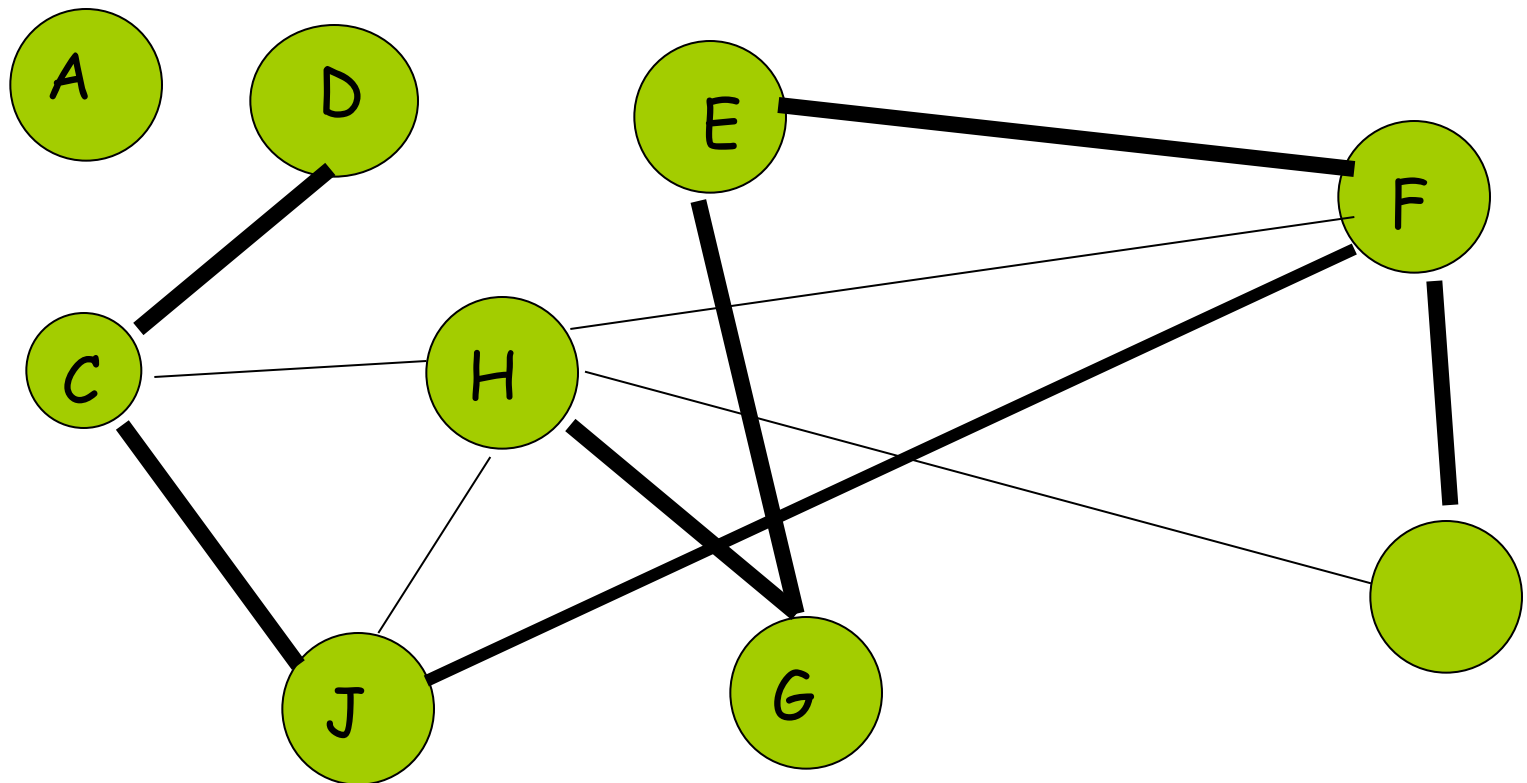
Talk outline:

1. KEY IDEA
2. The Odd hash function
3. Updating MST
4. Static MST
5. Updating ST
6. OPEN problems for distributed and sequential dynamic graphs.

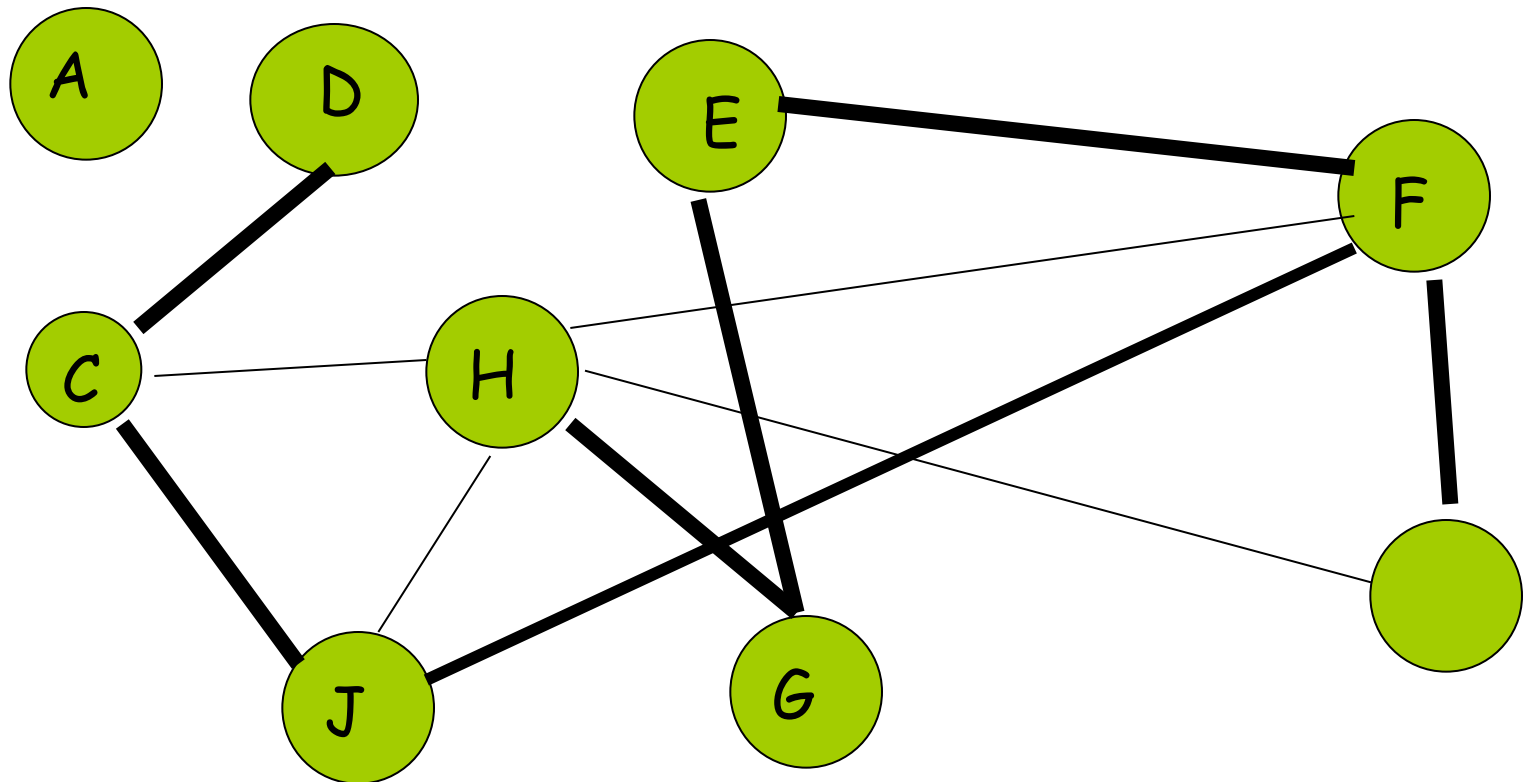
KEY IDEA:

- C a maximally connected component of a graph.
→ the sum of the degrees of the nodes in C is **even**, since every edge incident to a node in C contributes 2.
- If C is not maximally connected,
→ the sum of degrees of the nodes in C of a random subset of edges is **odd** with prob $1/2$.

basic communication step:
broadcast and return



How do we randomly sample and report results efficiently?



Recall:

Goal is to find (min weight) edge with only one endpoint in the tree

Odd hash function F

For any set S , we design hash

$$F:\{\text{weights}\}\rightarrow\{0,1\}$$

s.t. there is a constant probability $(1/36)$ that an ODD number of its elements hash to 1, iff S is non empty. Else it is 0.

Applying the Odd hash function F

Let $E' = \{\text{edges incident to nodes in tree } T_x\}$

$\text{XOR } F(e)$ (over all e is incident to a node in T_x)
 $= \text{XOR } F(e)$ (over all e with one endpoint in T_x)

$= 1$ with prob. $1/36$ unless the cut is empty.

Using the ODD Hash function:
TEST if there is a Replacement edge

- When a tree edge $\{X, Y\}$ is deleted, if $X < Y$
- X becomes leader, broadcasts Odd hash F to other nodes in tree T_x .
- Each node applies F to their set of incident edges and computes the XOR;
- XOR is taken over all nodes in T_x
- Repeat in parallel $O(\log n)$ times to get prob error $1/n^c$
- Output 1 iff any one XOR = 1

Find min wt replacement edge

(assuming distinct wts)

- Use binary search over the range of possible weights, testing w.h.p each time if there is a replacement edge in that wt range and narrowing the range.
- Return weight when only one is left.

Analysis

- \lg (Weight range) tests* cost of test
- Cost of test = initial cost of sending $\log n$ hash functions, +
+ 1 broadcast and return for each phase of the binary search
- Total = $O(n \log^2 n)$ messages

Constructing the Odd hash function

- Let U be the universe of elements.
- S a subset of U .
- $F(x) \rightarrow \{0,1\}$
- We want:

$$\text{XOR}_{\{y \text{ in } S\}} F(y) = 1$$

iff S is non empty

Odd hash function F

Obvious approach takes $O(\log n)$ hashes

F has two parts,

- a 2-wise independent hash function

$$h: U \rightarrow U$$

- t , a random element of U

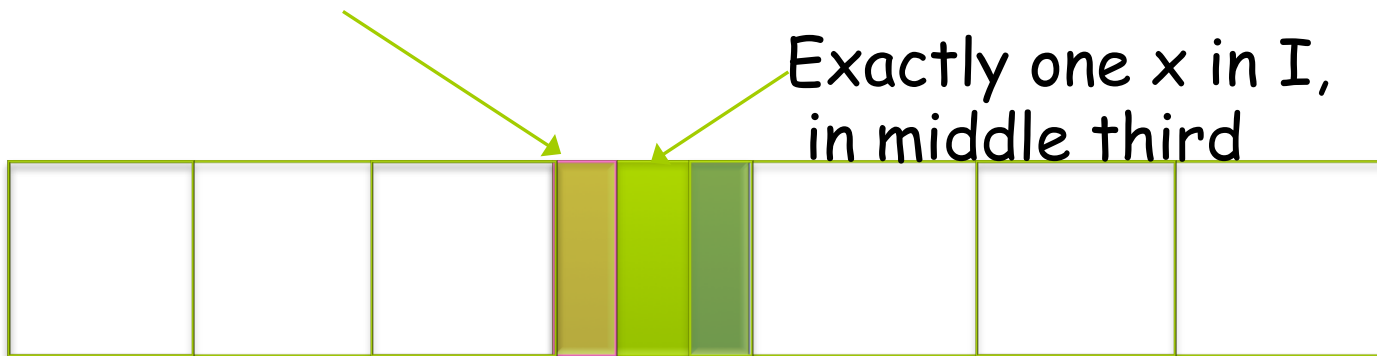
DEF: $F(s)=1$ iff $h(s) < t$

Note: F can be described in $O(\log n)$ bits.

Why F is an Odd hash function

- h hashes $U \rightarrow U$
- Imagine $2|S|$ equal sized intervals.

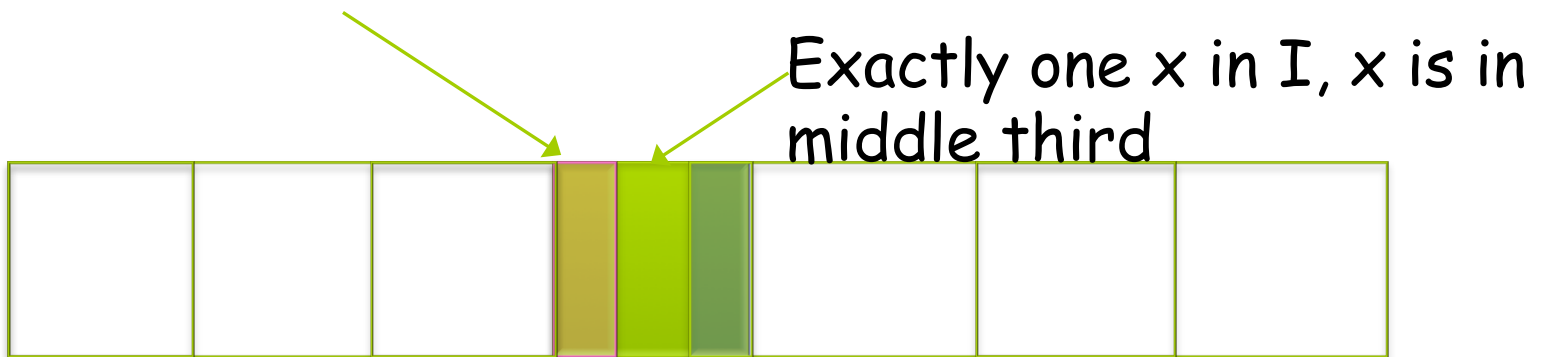
T lands in some I , in top third or bottom third



CASE: F works if

Parity of elements hashed to intervals left of I is

- Odd and t is in bottom third or
 - Even and t is in top third
- T lands in some I, and either top third or bottom third of I



Static synchronous MST alg

- While $I < \log n$
- Repeat:
- Each component finds min wt edge incident to it, sends message to other endpoint, and waits n time steps. Then the found edges are inserted to form larger components.

Log n phases, each takes $\log n$ broadcasts and returns, for a total of $O(n \log^2 n)$ expected message communication.

Find *any* edge in
expected $O(1)$ broadcasts and
returns

STEP 1: (IF step) Determine *if* there is a
replacement edge w.h.p.

- Use deterministic amplification to send out $O(\log n)$ bits which can be used by individual nodes to deterministically generate $\log n$ Odd Hash functions s.t one is good w.h.p.
- Return $\log n$ outputs using ONE return

STEP 2: (find) If there is a replacement edge, find it

- Broadcast a single 2-wise independent hash function h
- For $i=0, \dots, 2 \lg n$, every node x computes one word whose i^{th} bit =

$$\text{XOR}_{y \text{ incident to } x} h(y) \leq 2^i$$

- If XOR over tree $\neq 0$, $\text{min} \leftarrow$ first $i \neq 0$
- Test if there is exactly one edge with $h(y) \leq 2^{\text{min}}$. If so, return it.
- Else Repeat find.

Open problem and discussion

- Can we avoid the $O(m)$ communication costs of Gallagher for the asynchronous static model?
- Why this method is more complicated for sequential dynamic graph problem
- How the sequential dynamic graph method is not fully understood

Open problems for Sequential dynamic ST

- How to apply it to MST
- How to bring it down to $O(\log^3 n)$?
- Can we remove the tiers?