

Some practical and theoretical issues in computational ergodic theory

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Introducing the problem

This talk is about a series of works joint with W. Bahsoun, S. Galatolo, M. Monge, X.Niu, F. Poloni and B. Saussol. The aim of our research is to rigorously estimate some quantities associated to a given dynamical system, effectively proving theorems regarding the behaviour of these systems.



About our results

We obtained results in the following areas:

- approximate the invariant measure
- give a rigorous upper bound for speed of decay of correlations/convergence to equilibrium
- approximate the diffusion coefficient
- approximate the linear response.

In this talk I will explain how we tackle the task of approximating the linear response under a random perturbation for some one dynamical systems, in the same setting as W. Bahsoun talk.



An example of approximation of the density in L^1

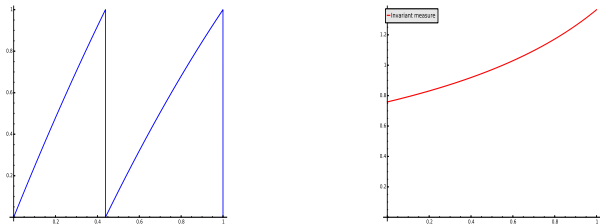


Figure: The approximated invariant density of the map $2x + \frac{1}{2}x(1-x) \bmod 1$

$$\|f - f_\delta\|_{L^1} \leq 1.7 \cdot 10^{-5}, \quad \delta = 2^{-25}$$

Theorem: The Lyapunov exponent for the Lanford map lies in $[1.312, 1.318]$ (old estimate) and the diffusion coefficient for the observable x^2 is contained in $[0.3458, 0.4152]$.



A geometric lorenz map

$$T(x) = \begin{cases} \theta|x - 1/2|^\alpha & 0 \leq x < 1/2 \\ 1 - \theta|x - 1/2|^\alpha & \frac{1}{2} < x \leq 1 \end{cases} \quad (1)$$

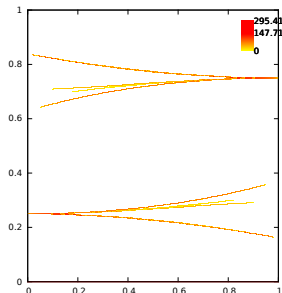
with constants $\alpha = 51/64$, $\theta = 109/64$, and

$$G(x, y) = \begin{cases} (y - 1/2)|x - 1/2|^\beta + 1/4 & 0 \leq x < 1/2 \\ (y - 1/2)|x - 1/2|^\beta + 3/4 & \frac{1}{2} < x \leq 1 \end{cases}$$

with $\beta = 396/256$.



The computed approximation



Theorem: the dimension of the attractor of this Lorenz map lies in the interval $[1.24063, 1.24219]$ (partition size 16384×1024).



The transfer operator

The main object of our investigation is the transfer operator:

$$L\mu(A) = \mu(T^{-1}A)$$

In the figure an approximation of the action of the transfer operator for the Lanford map.



The dynamical system

The strategy that we have developed works for dynamical systems $T : S^1 \rightarrow S^1$ such that $|T'(x)| > 1$ and $T \in C^3(S^1)$.

For those systems the following two Lasota-Yorke inequalities hold:

$$\begin{aligned}\|\mathcal{L}^n f\|_{\tilde{C}^1} &\leq M \cdot \lambda^n \|f\|_{\tilde{C}^1} + C \|f\|_{\infty} \\ \|\mathcal{L}^n f\|_{\tilde{C}^2} &\leq M(\lambda^2)^n \|f\|_{\tilde{C}^2} + D \|f\|_{\tilde{C}^1}.\end{aligned}$$

This implies that T has an a.c.i.m. f which lies in $C^2(S^1)$, and that, since f is continuous on the torus, f' lies in the space of average zero densities



The strategy for computing the linear response 1

As we saw in W. Bahsoun's talk, we want to approximate the linear response when we add a stochastic perturbation.

Let $\varepsilon \in (0, 1)$. For $f \in L^\infty(\mathbb{T})$ let K_ε denote the operator defined as:

$$K_\varepsilon f(x) = \int_{\mathbb{T}} \varepsilon^{-1} j(\varepsilon^{-1}(x - y)) f(y) dy,$$

where $j \in C^\infty(\mathbb{R}, \mathbb{R}^+)$, $\text{supp}(j) \subset [-1/2, 1/2]$ and $\int_{\mathbb{R}} j(y) dy = 1$.

Denote $L_\varepsilon = K_\varepsilon L$ and by f_ε its fixed point. We want to compute \tilde{h} such that

$$\lim_{\varepsilon \rightarrow 0} \left\| \frac{f_\varepsilon - f}{\varepsilon} - \tilde{h} \right\|_{C^0} = 0.$$



The strategy for computing the linear response 2

We want to approximate:

$$(\text{Id} - L)^{-1} \hat{L}f = \sum_{i=0}^{+\infty} L^i \hat{L}f,$$

where $Lf = f$ and $\hat{L}f = \gamma f'$ and this equality is true since $\hat{L}f$ is in the space of average 0 measures, where $\gamma := \int j(\xi) |\xi| d\xi$ and j is the convolution kernel that gives the random perturbation.



The strategy for computing the linear response 3

The main idea behind the strategy is the following:

- find a rigorous approximation g of $\hat{L}f$ (we need a discretization of L acting on C^2)
- estimate the tail of the sum $\sum_{i=0}^{+\infty} L^i g$
- approximate $L^i g$ by iterating a discretized operator (we need a discretization of L acting on C^1).



General ideas about discretizations

Knowing that an operator satisfies a L-Y inequality with respect to a strong norm and a weak norm

$$\|L^n f\|_s \leq A\lambda^n \|f\|_s + B\|f\|_w$$

The idea about discretization Π_η is that they have to be well behaved with respect to the same couple of norms

$$\|\Pi_\eta f\|_s \leq P_s \|f\|_s, \quad \|\Pi_\eta f\|_w \leq P_w \|f\|_w + \eta Q_w \|f\|_s$$

This permits us to prove a L-Y for a $\Pi_\eta L^k \Pi_\eta$, ensuring spectral stability.

Many people have been working in the topic of approximation of invariant measures using Ulam type approximations

[Bahsoun, Bose, Dellnitz, Ding, Froyland, Ippei, Junge, Li, Liverani, Murray, Padberg, Gehle, Tehresu...]

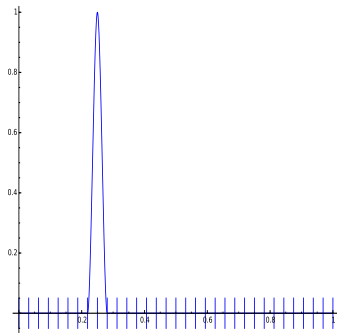


A C^1 partition of unity

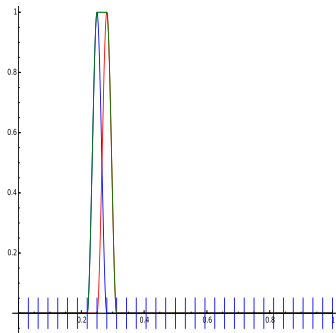
Let

$$\phi(x) = \begin{cases} 1 - 3x^2 - 2x^3 & x \in [-1, 0] \\ 1 - 3x^2 + 2x^3 & x \in [0, 1] \end{cases} . \quad (2)$$

Fix m , we define a partition of unity by $\phi_{i,m}(x) = \phi(m \cdot x - i)$,
 $i = 0, \dots, m$.



: $\phi_{8,32}(x)$



: $\phi_{8,32}(x) + \phi_{9,32}(x)$



A C^1 discretization

Denote by $\eta = 1/m$ the C^1 discretization we use is the following:

$$\Pi_\eta(f)(x) := \sum_i f(a_i) \cdot \phi_i(x) + \left(\int_0^1 f dm - \sum_{i=0}^m f(a_i) \int_0^1 \phi_i dm \right) \kappa(x),$$

where $\kappa(x) = 2 \sum_{j=0}^m \phi_{2j+1,2m}(x)$, and it is used to ensure that $\int \Pi_\eta f dx = \int f dx$.

We have that:

- 1 $\|\Pi_\eta f\|_\infty \leq 5\|f\|_\infty$;
- 2 $\|\Pi_\eta f\|_\infty \leq \|f\|_\infty + 2\frac{\|f'\|_\infty}{m}$;
- 3 $\|\Pi_\eta f\|_{\tilde{C}^1} \leq \frac{11}{2}\|f\|_{\tilde{C}^1}$;
- 4 $\|\Pi_\eta f - f\|_\infty \leq 3\frac{\|f'\|_\infty}{m}$;



A C^2 discretization

Define:

$$\tilde{g}(x) := \sum_i f'(a_i) \cdot \phi_i(x).$$

We define the operator

$$\tilde{\Pi}_\eta(f)(x) := \left(\int f dx - I(f) \right) + \int_0^x \tilde{g}(\xi) d\xi,$$

This projection also satisfies similar inequalities.



Approximating fixed points

Suppose f and f_δ are fixed points of L and L_δ and that

- $\|Lf - L_\delta f\|_w \leq K\delta$,
- there exists N such that $\|L_\delta^N g\| \leq \alpha \|g\|_w$ for all g with zero average
- $\|L_\delta^i\|_w \leq C_i$ for all $i = 0, \dots, N-1$

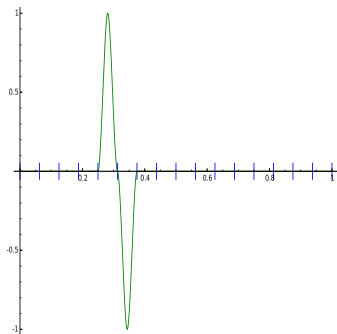
then

$$\|f - f_\delta\| \leq \frac{1}{1-\alpha} K\delta \sum_{i=0}^{N-1} C_i$$

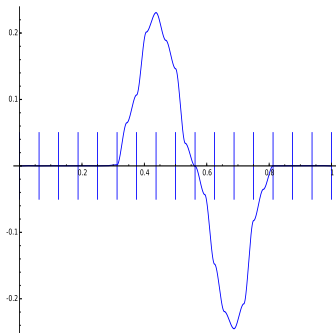


The HMCHUCAC principle, i.e., some ideas about resolution

How Mathematics Can Help Us in the Contemporary Age of Computation?



: In the kernel



: After 2 iterations, out of the kernel

Acting a C^0 approximation for the transfer operator of the Lanford map.



Coarse-Fine inequalities

Given two discretizations L_δ and $L_{\tilde{\delta}}$ and knowing that $\|L_\delta|_V\|_w \leq \alpha$ we want to find $\tilde{N}, \tilde{\alpha}$ such that $\|L_{\tilde{\delta}}^{\tilde{N}}|_V\| \leq \tilde{\alpha}$.

If the projections is well behaved:

$$\|L_\delta^k f - L_{\tilde{\delta}}^k f\|_w \leq \delta C \|f\|_s + \delta k D \|f\|_w.$$

Therefore:

$$\begin{aligned} \|L_{\tilde{\delta}}^N f\|_w &\leq \|L_\delta^N f\|_w + \|L_\delta^N f - L_{\tilde{\delta}}^N f\|_w \\ &\leq \alpha \|f\|_w + \delta C \|f\|_s + \delta k D \|f\|_w. \end{aligned}$$

To get a usable inequality we look at:

$$\|L_{\tilde{\delta}}^{N+K} f\|_w \leq M \alpha \|f\|_w + \delta C \lambda^k \|f\|_s + \delta C B \|f\|_w + \delta k D M \|f\|_w,$$

since $L_{\delta'}$ acts on a finite dimensional space $\|f\|_s \leq \Gamma \|f\|_w$.



Estimating the convergence to equilibrium and the tails

In the talk by Stefano Galatolo, was explained how, by knowing that $\|L_\delta^N|_V\|_w \leq \alpha$, it is possible to estimate a , b and ρ such that

$$\|L^{kN}g\|_w \leq \frac{1}{a}\rho^k\|g\|_s$$
$$\|L^{kN}g\|_s \leq \frac{1}{b}\rho^k\|g\|_s$$



Bounding the iteration error

Suppose there are two norms $\|\cdot\|_s \geq \|\cdot\|_w$, such that $\forall f \in \mathcal{B}, \forall n \geq 1$

$$\|\mathcal{L}^n f\|_s \leq A\lambda_1^n \|f\|_s + B\|f\|_w. \quad (3)$$

Let π_δ be a finite rank operator satisfying:

- $\mathcal{L}_\delta = \pi_\delta \mathcal{L} \pi_\delta$ with $\|\pi_\delta v - v\|_w \leq K\delta \|v\|_s$;
- $\pi_\delta, \mathcal{L}^i$ and \mathcal{L}_δ^i are bounded for the norm $\|\cdot\|_w$: $\|\pi_\delta\|_w \leq P$ and $\forall i > 0, \|\mathcal{L}^i\|_w \leq M, \|\mathcal{L}_\delta^i\|_w \leq M_\delta$.

Then

$$\begin{aligned} \|(\mathcal{L} - \mathcal{L}_\delta)f\|_w &\leq K\delta(A\lambda_1 + P)\|f\|_s + K\delta B\|f\|_w \\ \|\mathcal{L}^n f - \mathcal{L}_\delta^n f\|_w &\leq \delta K M_\delta \left(\frac{(A\lambda_1 + P)A}{1 - \lambda_1} \|f\|_s + nB(A\lambda_1 + P + M)\|f\|_w \right) \end{aligned}$$



One experiment

Let

$$T_0(x) = S(x) + P(x) + 0.005 \cdot \sin(64\pi \cdot x),$$

where

$$S(x) = \frac{31x}{1-x}.$$

Let

$$T_1(x) = 32x - 1 + 0.005 \cdot \sin(64\pi \cdot x).$$

Define

$$T(x) : \begin{cases} T_0(x - 2k/32), & x \in [2k/32, (2k + 1)/32] \\ T_1(x - (2k + 1)/32), & x \in [(2k + 1)/32, (2k + 2)/32], \end{cases} \quad (4)$$

where $k = 0, 1, \dots, 15$.



Plot of the dynamic

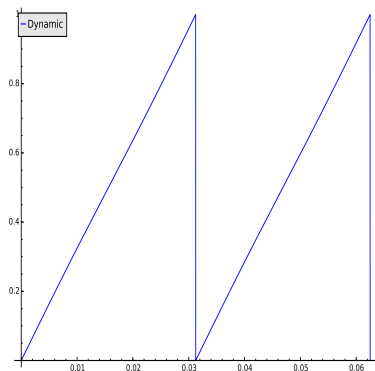
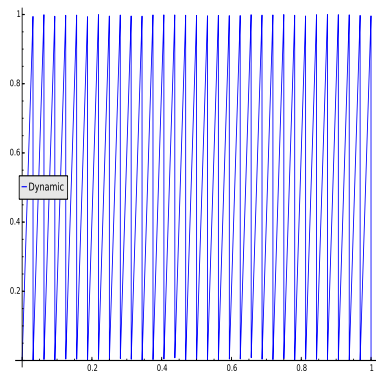


Figure: The graph of the map T as defined in (4)



The approximation of the linear response

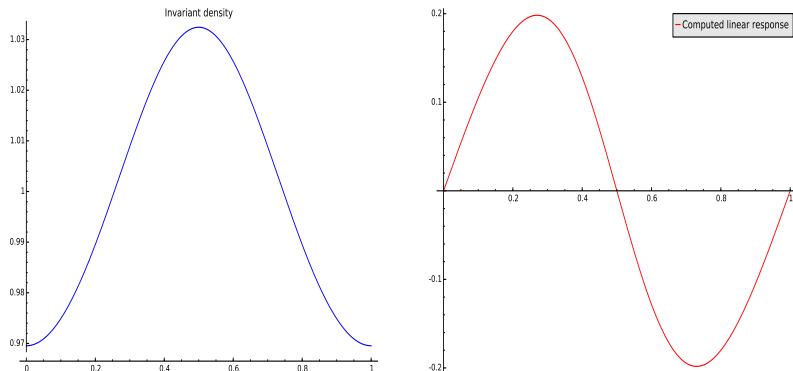


Figure: The density and its linear response



Some numbers about the experiment

Partition size for the estimate of the convergence to equilibrium in C^0 :
1/65536.

Partition size of the C^1 partition: 1/4194304.

Partition size of the C^2 partition: 1/4194304.

Rigorous error:

$$\|\hat{h} - \gamma \sum_{k=0}^{14} \mathcal{L}_\eta^k \tilde{f}_\eta\|_\infty \leq 0.044\gamma.$$

