

∞ -Variate Integration

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Presentation based on papers co-authored with

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INFORMATION-BASED COMPLEXITY approach
very nicely explained in **Houman Owhadi's** tutorial:
many thanks Houman

Briefly: instead of working with specific functions,
IBC deals with problems on whole spaces of functions
and tries to determine
the **complexity**, i.e., the minimal cost,
and (almost) **optimal algorithms**.

This is done in various settings including:
worst case, average case and randomized settings

"Classical" Integration Problem

Given a normed space F of functions on $[0, 1]^d$

approximate $I(f) = \int_{D^d} f(\mathbf{x}) \, d\mathbf{x}$

by cubatures $Q_n(f) = \sum_{j=1}^n f(\mathbf{t}_{n,j}) \cdot a_{n,j}$

with small error $\|I - Q_n\|$ and

(if possible) small cost

Classical Methods are **Extremely Bad!!!!**
even for Finitely Many Variables.

(Product) Trapezoidal T_n with n samples has error

$$\text{error}(T_n; d = 2) \simeq \frac{1}{n} \quad d = 2 \text{ variables}$$

$$\text{error}(T_n; d = 360) \simeq \frac{1}{n^{2/360}} \quad d = 360 \text{ variables}$$

E.g., for 360 variables, it needs

$$n \sim 20^{180} \text{ to get only } 1 \text{ digit of accuracy}$$

$$20^{180} =$$

1532495540865888858358347027150309183618739122
 183602176000
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For Classical (Isotropic) Spaces

One **Cannot Do Better**

“Curse of Dimensionality”

For Classical (Isotropic) Spaces

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To Break this Curse

Different Spaces Are Needed

Weighted Spaces

treat different variables differently

Motivating Example

Compute expectation $\mathbb{E}(g(\mathbf{X}(t_0)))$ for
stochastic process $\mathbf{X}(t) = \sum_{j=1}^{\infty} x_j \xi_j(t)$

Equivalent to computing an integral of

$$f(x_1, x_2, \dots) = g \left(\sum_{j=1}^{\infty} x_j \xi_j(t_0) \right)$$

In $g \left(\sum_{j=1}^{\infty} x_j \xi_j(t_0) \right)$

“importance” of x_j

is quantized by the size of $|\xi_j(t_0)|$.

The larger $|\xi_j(t_0)|$ the more important x_j .

Although there are results for quite general spaces and problems

we present results for **Integration**
over a **special space \mathcal{F}**

\mathcal{F} is the γ -weighted Banach space
of functions with dominating mixed derivatives
of order one bounded in L_p -norm

Notation:

\mathfrak{w} finite subsets of \mathbb{N}_+

listing the “variables in action”

Given $\mathbf{x} = (x_1, x_2, \dots)$, $\mathbf{x}_{\mathfrak{w}} = (x_j : j \in \mathfrak{w})$

$[\mathbf{x}_{\mathfrak{w}}; \mathbf{0}] = (y_1, y_2, \dots)$ with $y_j = \begin{cases} x_j & \text{if } j \in \mathfrak{w}, \\ 0 & \text{if } j \notin \mathfrak{w} \end{cases}$

$$f^{(\mathfrak{w})} = \frac{\partial^{|\mathfrak{w}|}}{\partial \mathbf{x}_{\mathfrak{w}}} f = \prod_{j \in \mathfrak{w}} \frac{\partial}{\partial x_j} f$$

Domain: $D^{\mathbb{N}}$ set of sequences $(x_j)_{j \in \mathbb{N}}$ with $x_j \in D$;
for simplicity $D = [0, 1]$.

\mathcal{F} the Banach space of $f : D^{\mathbb{N}} \rightarrow \mathbb{R}$
endowed with the norm

$$\|f\|_{\mathcal{F}} = \left(\sum_{\mathfrak{w}} \gamma_{\mathfrak{w}}^{-p} \|f^{(\mathfrak{w})}([\cdot; \mathbf{0}])\|_{L_p(D^{|\mathfrak{w}|})}^p \right)^{1/p} < \infty$$

Here $p \in [1, \infty]$ and $\gamma_{\mathfrak{w}} \geq 0$ are *weights*

For simplicity

Product Weights introduced by

[Sloan and Woźniakowski 1998]:

$$\gamma_{\mathfrak{w}} = c \prod_{j \in \mathfrak{w}} \gamma_j \quad (\gamma_j = j^{-\beta})$$

For ‘**motivating example**’ we have

$$\gamma_{\mathfrak{w}} \simeq \prod_{j \in \mathfrak{w}} |\xi_j(t_0)|^\alpha$$

Integration Problem

APPROXIMATE:

$$\begin{aligned}\mathcal{I}(f) &:= \int_{D^{\mathbb{N}}} f(\mathbf{x}) \, d^{\mathbb{N}}\mathbf{x} \\ &= \lim_{d \rightarrow \infty} \int_{D^d} f(x_1, \dots, x_d, 0, 0, \dots) \, d[x_1, \dots, x_d]\end{aligned}$$

Integration Problem

APPROXIMATE:

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We have

$$\|\mathcal{I}\| = \left(\sum_{\mathfrak{w}} \gamma_{\mathfrak{w}}^{p^*} / (1 + p^*)^{|\mathfrak{w}|} \right)^{1/p^*} \quad \left(= \max_{\mathfrak{w}} \gamma_{\mathfrak{w}} \text{ for } p = 1 \right)$$

ASSUMPTIONS:

(A1) $\|\mathcal{I}\| < \infty$

(A2) We can sample f at points $[\mathbf{x}_m; \mathbf{0}]$

For 'motivating example' we have:

$$f([\mathbf{x}_m; \mathbf{0}]) = g \left(\sum_{j \in m} x_j \xi(t_0) \right)$$

How to Cope with So Many Variables?

- (i) **Truncate the dimension**, i.e.,
approximate the integral of

$$f(x_1, \dots, x_k, 0, 0, \dots)$$

or (even better)

- (ii) use

Multivariate Decomposition Method

Low Truncation Dimension

[Kritzer, Pillichshammer, W. 2016] \subset [Hinrichs, Kritzer, Pillichshammer, W.]

Let

$$f_k(x_1, \dots, x_k) = f(x_1, \dots, x_k, 0, 0, \dots)$$

Given the **error demand** $\varepsilon > 0$,
 $\dim^{\text{trnc}}(\varepsilon)$ **ε -truncation dimension**
the smallest k such that

$$|\mathcal{I}(f) - \mathcal{I}(f_k)| \leq \varepsilon \|f\|_{\mathcal{F}} \quad \text{for all } f \in \mathcal{F}$$

Our concept of **Truncation Dimension**
is different than the one in Statistics!!!

If

$$|\mathcal{I}(f) - \mathcal{I}(f_k)| \leq \varepsilon \|f\|_{\mathcal{F}} \quad \text{and} \quad |\mathcal{I}(f_k) - Q_k(f_k)| \leq \varepsilon \|f\|_{\mathcal{F}}$$

then

$$|\mathcal{I}(f) - Q_k(f_k)| \leq 2\varepsilon \|f\|_{\mathcal{F}}$$

Hence

the smaller $\dim(\varepsilon)$ the better

Special Case: $\gamma_{\mathfrak{w}} = c \prod_{j \in \mathfrak{w}} j^{-\beta}$

$$\dim^{\text{trnc}}(\varepsilon) \leq \min \left\{ \ell : \sum_{j=\ell+1}^{\infty} j^{-\beta p^*} \leq \frac{p^* + 1}{c p^*} \ln(1/(1 - \varepsilon^{p^*})) \right\}$$

$$= O\left(\varepsilon^{-1/(\beta-1+1/p)}\right)$$

for $p > 1$ and

$$\dim^{\text{trnc}}(\varepsilon) = \left\lceil \left(\frac{c}{\varepsilon}\right)^{1/\beta} \right\rceil - 1$$

for $p = 1$

Specific Values of $\mathbf{dim}^{\text{trnc}}(\varepsilon)$ for $p = 1$ and $\gamma_{\mathfrak{w}} = \prod_{j \in \mathfrak{w}} j^{-\beta}$

ε	10^{-1}	10^{-2}	10^{-3}	10^{-4}	10^{-5}	
$\mathbf{dim}^{\text{trnc}}(\varepsilon)$	2	9	31	99	316	$\beta = 2$
$\mathbf{dim}^{\text{trnc}}(\varepsilon)$	2	4	9	21	46	$\beta = 3$
$\mathbf{dim}^{\text{trnc}}(\varepsilon)$	1	3	5	9	17	$\beta = 4$

For instance, for the error demand $\varepsilon = 10^{-3}$ with $\beta = 4$,

only five variables instead of ∞ -many!

Worst Case Error of QMC or Sparse Grids Methods is:

$$\leq O\left(\frac{\ln^4 n}{n}\right)$$

Multivariate Decomposition Method

MDM replaces
one ∞ -variate integral
by
only few integrals
each with
only few variables

Introduced in [Kuo, Sloan, W., and Woźniakowski 2010]

Any function f has the unique
anchored decomposition

$$f(\mathbf{x}) = \sum_{\mathfrak{w}} f_{\mathfrak{w}}(\mathbf{x}_{\mathfrak{w}}),$$

where $f_{\mathfrak{w}}$ depends only on x_j with $j \in \mathfrak{w}$
and vanishes if $x_j = 0$.

General Idea:

- Select the "**most important**" \mathfrak{w} 's
- Approximate Integrals of $f_{\mathfrak{w}}$ **only** for the selected \mathfrak{w} 's

More precisely:

Given the **error demand** $\varepsilon > 0$,
construct an **“active set”** $\text{Act}(\varepsilon)$
of subsets \mathfrak{w} such that

$$\left| \mathcal{I} \left(\sum_{\mathfrak{w} \notin \text{Act}(\varepsilon)} f_{\mathfrak{w}} \right) \right| \leq \frac{\varepsilon}{2} \|f\|_{\mathcal{F}} \quad \text{for all } f \in \mathcal{F}.$$

Do nothing for integrals of $f_{\mathfrak{w}}$ with $\mathfrak{w} \notin \text{Act}(\varepsilon)$

For $\mathfrak{w} \in \mathbf{Act}(\varepsilon)$, choose $n_{\mathfrak{w}}$ and cubatures $Q_{\mathfrak{w}, n_{\mathfrak{w}}}$

to approximate integrals of $f_{\mathfrak{w}}$ such that

$$\sum_{\mathfrak{w} \in \mathbf{Act}(\varepsilon)} |\mathcal{I}(f_{\mathfrak{w}}) - Q_{\mathfrak{w}, n_{\mathfrak{w}}}(f_{\mathfrak{w}})| \leq \frac{\varepsilon}{2} \|f\|_{\mathcal{F}} \quad \text{for all } f \in \mathcal{F}.$$

The cubatures $Q_{\mathfrak{w}, n_{\mathfrak{w}}}$ could be **QMC** or **Sparse Grids**

Then the **MDM** given by

$$Q_\varepsilon(f) := \sum_{\mathfrak{w} \in \mathbf{Act}(\varepsilon)} Q_{\mathfrak{w}, n_{\mathfrak{w}}}(f_{\mathfrak{w}})$$

has the "**worst case error**" bounded by ε , i.e.,

$$|\mathcal{I}(f) - Q_\varepsilon(f)| \leq \varepsilon \|f\|_{\mathcal{F}} \quad \text{for all } f \in \mathcal{F}.$$

How about the **COST**?

The number of integrals to approximate is small:

$$\mathbf{card}(\varepsilon) := |\mathbf{Act}(\varepsilon)| = \mathcal{O}\left(\frac{1}{\varepsilon}\right)$$

Each $f_{\mathfrak{w}}$ depends on only $|\mathfrak{w}|$ variables.

The largest number of variables is also small:

$$\mathbf{dim}(\varepsilon) := \max \{|\mathfrak{w}| : \mathfrak{w} \in \mathbf{Act}(\varepsilon)\} = \mathcal{O}(???)$$

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The largest number of variables is also small:

$$\mathbf{dim}(\varepsilon) := \max\{|\mathfrak{w}| : \mathfrak{w} \in \mathbf{Act}(\varepsilon)\} = \mathcal{O}\left(\frac{\ln(1/\varepsilon)}{\ln(\ln(1/\varepsilon))}\right)$$

[Plaskota and W. 2011]

$\mathbf{dim}(\varepsilon)$ is like

Superposition Dimension in Statistics

Very efficient algorithm to construct $\mathbf{Act}(\varepsilon)$ in [Gilbert and W. 2016]

Specific Values of $\dim(\varepsilon)$ and $\text{card}(\varepsilon)$ for $p = 1$ and $\gamma_w = \prod_{j \in w} j^{-\beta}$

ε	10^{-1}		10^{-2}		10^{-3}		10^{-4}		10^{-5}		
	2	6	3	22	4	113	4	534	5	2424	$\beta = 2$
	2	6	2	8	3	22	3	68	4	192	$\beta = 3$
	1	2	2	6	2	10	3	26	3	50	$\beta = 4$

For instance, for $\varepsilon = 10^{-3}$ with $\beta = 4$

it is sufficient to approximate

10 integrals with at most 2 variables!

Active Set $\text{Act}(10^{-3})$ For $\beta = 4$ $\emptyset,$ $\{1\}, \{2\}, \{3\}, \{4\}, \{5\},$
 $\{1, 2\}, \{1, 3\}, \{1, 4\}, \{1, 5\}$ For $\beta = 3$ $\emptyset,$ $\{1\}, \{2\}, \{3\}, \{4\}, \{5\}, \{6\}, \{7\}, \{8\}, \{9\},$
 $\{1, 2\}, \{1, 3\}, \{1, 4\}, \{1, 5\}, \{1, 6\}, \{1, 7\}, \{1, 8\}, \{1, 9\}, \{2, 3\}, \{2, 4\},$
 $\{1, 2, 3\}, \{1, 2, 4\}$

For $\beta = 2$

31 of integrals with 1 variable

54 of integrals with 2 variables

26 of integrals with 3 variables

2 of integrals with 4 variables

\emptyset ,

$\{1\}, \dots, \{31\}$,

$\{1, 2\}, \dots, \{1, 31\}, \{2, 3\}, \dots, \{2, 15\}$,

$\{3, 4\}, \dots, \{3, 10\}, \{4, 5\}, \{4, 6\}, \{4, 7\}, \{5, 6\}$,

$\{1, 2, 3\}, \dots, \{1, 2, 15\}, \{1, 3, 4\}, \dots, \{1, 3, 10\}$,

$\{1, 4, 5\}, \{1, 4, 6\}, \{1, 4, 7\}, \{1, 5, 6\}, \{2, 3, 4\}, \{2, 3, 5\}$,

$\{1, 2, 3, 4\}, \{1, 2, 3, 5\}$

REMARK:

We do **NOT** know $f_{\mathfrak{w}}$ terms. However, we can sample them. Indeed due to [Kuo, Sloan, W., and Woźniakowski 2010b]

$$f_{\mathfrak{w}}(\mathbf{x}_{\mathfrak{w}}) = \sum_{\mathfrak{v} \subseteq \mathfrak{w}} (-1)^{|\mathfrak{w}| - |\mathfrak{v}|} f([\mathbf{x}_{\mathfrak{v}}; \mathbf{0}])$$

requires

$2^{|\mathfrak{w}|}$ samples of f

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requires

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but from [Plaskota and W. 2011]

$$2^{|\mathfrak{w}|} = O\left(\varepsilon^{\frac{-1}{\ln(\ln(1/\varepsilon))}}\right) \text{ is small for modest } \varepsilon.$$

How About ANOVA Spaces?

$f \in \mathcal{F}^{\text{ANOVA}}$ iff

$$f(\mathbf{x}) = \sum_{\mathfrak{w}} f_{\mathfrak{w},A}(\mathbf{x}_{\mathfrak{w}})$$

with $\int_D f_{\mathfrak{w},A}(\mathbf{x}_{\mathfrak{w}}) dx_j = 0$ and

$$\|f\|_{\mathcal{F}^{\text{ANOVA}}} = \left(\sum_{\mathfrak{w}} \gamma_{\mathfrak{w}}^{-p} \|f_{\mathfrak{w},A}^{(\mathfrak{w})}\|_{L_p}^p \right)^{1/p} < \infty$$

ANOVA decomposition terms $f_{\mathfrak{w},A}$
cannot be sampled, i.e.,
low truncation dimension and MDM might
not be applicable.

Even worse: the 'easiest' (constant) term
is **NOT known**;
it is the integral we want:

$$f_{\emptyset,A} = \mathcal{I}(f)$$

HOWEVER

If the spaces are **EQUIVALENT, then
efficient algorithms for anchored spaces
are also efficient for ANOVA spaces**

This motivated the study of

Equivalence of anchored and ANOVA Spaces

For product weights $\gamma_w = \prod_{j \in w} j^{-\beta}$

$$\mathcal{F} = \mathcal{F}^{\text{ANOVA}} \quad \text{as sets.}$$

For the imbedding $\iota : \mathcal{F} \hookrightarrow \mathcal{F}^{\text{ANOVA}}$ we have

$$\|\iota\| = \|\iota^{-1}\| \leq \prod_{j=1}^{\infty} (1 + j^{-\beta})$$

EQUIVALENCE iff $\beta > 1$

Research direction initiated in [Hefter and Ritter 2014],
Hilbert spaces setting $p = 2$ and product weights

[Hefter, Ritter and W. 2016]
 $p \in \{1, \infty\}$ and general weights,

[Hinrichs and Schneider 2016]
 $p \in (1, \infty)$,

[Gnewuch, Hefter, Hinrichs, Ritter, and W. 2016]
more general spaces,

[Kritzer, Pillichshammer, and W. 2017]
sharp lower bounds,

[Hinrichs, Kritzer, Pillichshammer, and W. 2017] most general

GENERALIZATIONS

More General Domain:

Any interval D including $D = \mathbb{R}$

More General Distributions μ on D :

e.g., Exponential, Gaussian

More General Integrals: $\int_{\mathbb{R}^N} f(\mathbf{x}) \mu^{\mathbb{N}}(d\mathbf{x})$

Other Linear Solution Operators: $\mathcal{S}(f) = ???$

e.g., Function Approximation, ODE's, PDE's

General Information about f :

$$L_1(f), L_2(f), \dots, L_n(f), \quad L_j \in \mathcal{F}^*$$

Bayesian Approach:

Endowing \mathcal{F} with
Gaussian probability measure **PROB**
and studying **average case errors**:

$$\int_{\mathcal{F}} \|\mathcal{S}(f) - \text{Alg}(L_1(f), \dots, L_n(f))\|_{\mathcal{S}(\mathcal{F})}^p \text{PROB}(df)$$

Similar results in [W. 2014]

Comments to Houman Owhadi's 1st talk:

[Traub, W., and Woźniakowski 1988] has a number of chapters devoted to the average, randomized and probabilistic settings for **infinitely dimensional** Hilbert and Banach spaces. They are based on a number of earlier papers. Currently there are 100's of IBC such papers, see e.g. 3 Volumes monograph:

[E. Novak and H. Woźniakowski 2008-10]

On page 16, the **IBC Probabilistic Setting** was attributed to H. Woźniakowski's paper. However, as acknowledged in that paper, the results were based on some of the results of my paper:
Optimal algorithms for linear problems with Gaussian measures,
Rocky Mountains J. of Math. 1986,
where **IBC Probabilistic Setting** has been introduced for the first time.

Comment to Ilias Bilonis' talk:

Research that seem to be related:

IBC approach to PDE's with random coefficients
by Ch. Schwab and his collaborators,
e.g., F.Y.Kuo, D. Nuyens, I. H. Sloan

THANK YOU FOR THE ATTENTION