

Uncertainty Principles for Fourier Multipliers

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- ▶ **Question 2:** Why do we care about this setting?

Example 1: Gabor Systems and the Zak Transform

- ▶ Gabor System: For $g \in L^2(\mathbb{R})$,

$$G(g) := \{e^{2\pi imx} g(x - n)\}_{m,n \in \mathbb{Z}} = \{M_m T_n g\}_{m,n \in \mathbb{Z}}$$

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- ▶ **Leads to an isometric isomorphism:**
 - ▶ $L^2(\mathbb{R}) \rightarrow L^2_w(\mathbb{T}^2)$, for $w = |Zg|^2$
 - ▶ $G(g) \rightarrow E = E(2)$.

Example 2: Shift-Invariant Spaces and Periodization

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 - ▶ $V(f) \rightarrow L_w^2(\mathbb{T}^d)$, for $w = P\hat{f}$
 - ▶ $h \rightarrow m$
 - ▶ $T(f) \rightarrow E = E(d)$

Spanning and Independence Properties

Let \mathcal{H} be a Hilbert space, and $H = \{h_n\}_{n=1}^{\infty} \subset \mathcal{H}$.

Complete



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- ▶ Every frame is complete, with the additional bonus that there exist a choice of coefficients such that $h = \sum c_n h_n$ with

$$\|c_n\|_{l^2} \asymp \|h\|_{\mathcal{H}}.$$

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- ▶ Riesz basis \implies frame; Riesz basis \iff minimal frame.

(C_q) -systems (Olevskii, Nitzan '07)

- ▶ Fix $2 \leq q \leq \infty$. $\{h_n\}_{n=1}^\infty \subset \mathcal{H}$ is a (C_q) -system if for each $h \in \mathcal{H}$, h can be approximated to arbitrary accuracy by a finite sum $\sum a_n h_n$ such that

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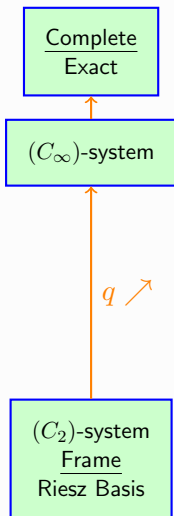
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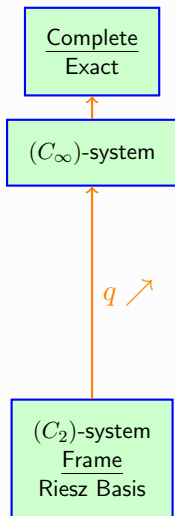
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- ▶ (C_q) -system \implies $(C_{q'})$ -system for all $q' \geq q$

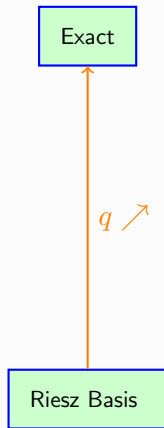
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For Exact E in $L_w^2(\mathbb{T}^d)$:



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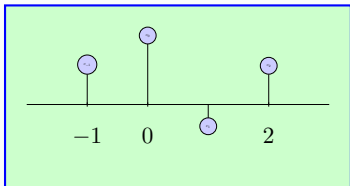
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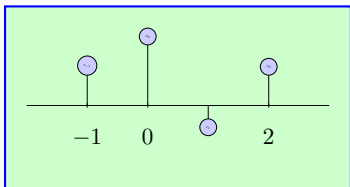
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- ▶ Nitzan, Olsen ('11) gave necessary and sufficient conditions similar to the fourth characterization

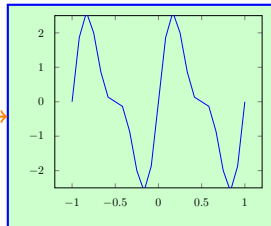
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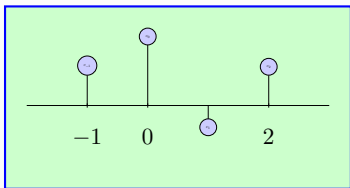
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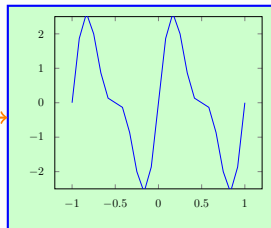
\hat{c}



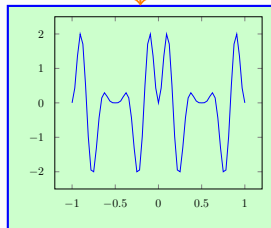
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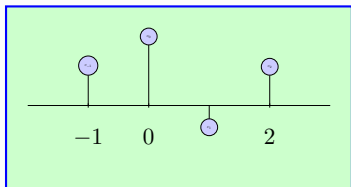
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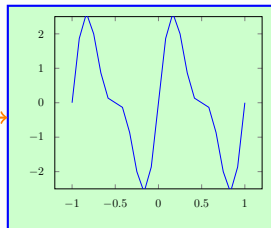
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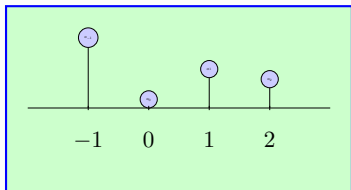
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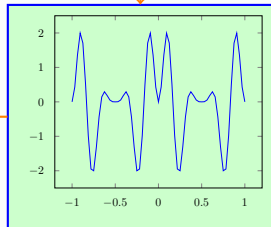
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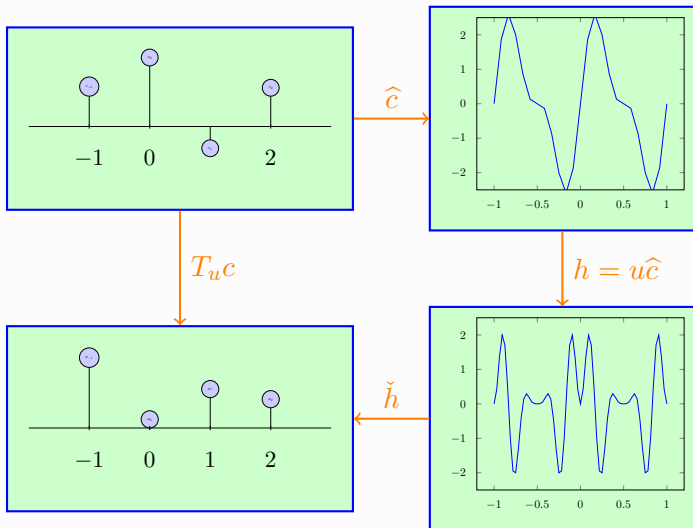
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 - ▶ $\mathcal{M}_2^\infty = L^2(\mathbb{T}^d)$ (Agrees with minimal system characterization)

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Sobolev Space:

$$H^s(\mathbb{T}^d) = \{f \in L^2(\mathbb{T}^d) : \sum_{k \in \mathbb{Z}^d} |k|^{2s} |\widehat{f}(k)|^2 < \infty\}$$

Results with a single zero

Theorem (Nitzan, M.N., Powell)

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1. If $\frac{d}{2} \leq s < \frac{d}{2} + 1$, then $u = \frac{1}{w} \notin \mathcal{M}_2^q$ for any q satisfying $2 \leq q \leq \frac{d}{d-s}$.

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- ▶ Proof relies on Sobolev Embedding Theorem in Hölder spaces.
- ▶ For $s > \frac{d}{2} + 1$, we can't say more than the bound in part 2 unless we require a zero of a larger order.

Zero Sets of Larger Hausdorff Dimension

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- ▶ A similar question was studied by Jiang, Lin ('03) and Schikorra ('13) with the Fourier multiplier condition replaced with an integrability condition.

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- ▶ Proof uses a version of Poincare Inequality from Jiang, Lin ('03) and Schikorra ('13).

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Let $f \in L^2(\mathbb{R})$. If $\mathcal{G}(f) = \{e^{2\pi imx} f(x - n)\}_{m,n \in \mathbb{Z}}$ is a Riesz basis for $L^2(\mathbb{R})$, then

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- ▶ The Riesz basis property forces $|Zf| \geq A > 0$, which gives contradiction.

Sharp (C_q) -system BLT

Theorem (Nitzan, M.N, Powell)

Fix $q > 2$. If $\mathcal{G}(f, 1, 1) = \{e^{2\pi imx} f(x - n)\}_{m,n \in \mathbb{Z}}$ is an exact (C_q) -system for $L^2(\mathbb{R})$, then

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- ▶ Nitzan, Olsen ('11) proved similar result, with an additional ϵ on the weight, as well as non-symmetric versions.
- ▶ The $q = \infty$ case gives the BLT for exact systems (originally due to Daubechies, Janssen ('93)) and nonsymmetric versions were given by Heil and Powell ('09)

Shift-Invariant Spaces with Extra Invariance

For a given shift-invariant space $V = V(f) \subset L^2(\mathbb{R}^d)$,

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- ▶ Aldroubi, Sun, Wang (2011), and Tessera, Wang (2014), showed that Balian-Low type results exist for shift-invariant spaces with extra-invariance.

(C_q) -system SIS BLT

Theorem (Nitzan, M.N., Powell)

Fix $2 \leq q \leq \infty$. Suppose that $f \in L^2(\mathbb{R})$ is nonzero and $V(f)$ is $\frac{1}{N}\mathbb{Z}$ -invariant. If $T(f)$ is a minimal (C_q) -system in $V(f)$, then

$$\int_{\mathbb{R}} |x|^{2(1-1/q)} |f(x)|^2 dx = \infty.$$

Equivalently, $\hat{f} \notin H^{1-1/q}(\mathbb{R})$.

- ▶ If $T(f)$ is a minimal system for $V(f)$, then $T(f)$ is a (C_∞) -system. Thus, the $q = \infty$ case gives us a result for minimal systems.
- ▶ (Hardin, M.N., Powell) In the $q = 2$ case, the result holds in higher dimensions, and without assuming minimality. (i.e., frames and not necessarily Riesz bases)

Minimal (C_q) -result Higher Dimensions

Theorem

Fix q such that $2 \leq q \leq \infty$, and let $s = \min(d(\frac{1}{2} - \frac{1}{q}) + \frac{1}{2}, 1)$. Let $0 \neq f \in L^2(\mathbb{R}^d)$, and suppose $V(f)$ is invariant under some non-integer shift. If $\mathcal{T}(f)$ is a minimal (C_q) -system for $V(f)$ then

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- ▶ Probably the sharp s is $1 - 1/q$ in all dimensions.

Where does the zero come from?

- ▶ Extra-invariance can be characterized in terms of $P\hat{f}$.
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- ▶ The condition is somewhat technical, so let's look at an example of $f \in L^2(\mathbb{R}^2)$ and $V(f)$ having $\frac{1}{2}\mathbb{Z}^2$ -invariance.

$$\begin{aligned}P(x) &= \sum_{k \in \mathbb{Z}^2} |\hat{f}(x - k)|^2 \\&= \sum_{k \in \mathbb{Z}^2} |\hat{f}(x - 2k)|^2 + \sum_{k \in \mathbb{Z}^2} |\hat{f}(x - 2k + e_1)|^2 \\&\quad + \sum_{k \in \mathbb{Z}^2} |\hat{f}(x - 2k + e_2)|^2 + \sum_{k \in \mathbb{Z}^2} |\hat{f}(x - 2k + e_1 + e_2)|^2 \\&= P_2(x) + P_2(x + e_1) + P_2(x + e_2) + P_2(x + e_1 + e_2).\end{aligned}$$

- ▶ $V(f)$ is $\frac{1}{2}\mathbb{Z}^2$ -invariant iff $P_2(x)$ and its shifts have disjoint support.

Thanks

Thanks!!!